

Polynomial Filtering for a Single Fermion Flavour in Lattice QCD

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Introduction

- The dominant expense of Lattice QCD is generating dynamical gauge field configurations.
- Hybrid Monte Carlo (HMC) is still the most used algorithm for generating dynamical configurations.
- There have been many improvements to the basic HMC algorithm developed over the years.
- A partial list of “multi-scale” type algorithmic improvements:
 - Domain Decomposition method (Luscher).
 - Mass Preconditioning (Hasenbuch).
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- We begin by reviewing the fundamentals of the HMC algorithm.

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Hybrid Monte Carlo Review

- The lattice is embedded in a Hamiltonian system by the addition of a fictitious “simulation” time τ , along with an additional fictitious field P which are the conjugate momenta to U ,

$$\mathcal{H}(P, U) = \sum_{x,\mu} \frac{1}{2} \text{Tr} P_\mu(x)^2 + S[U].$$

- The conjugate momenta $P_\mu(x)$ are drawn from a Gaussian distribution.
- In this way, the Hamiltonian \mathcal{H} is constructed so that after path integration the expectation values of observables are unaltered.
- Where are the fermions?

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Fermion Determinant

- The fermion fields ψ and $\bar{\psi}$ are Grassmannian, hence to perform simulations we need to integrate them out. We have that

$$\det D_w = \int \mathcal{D}\bar{\psi} \mathcal{D}\psi e^{-\int d^4x \bar{\psi}(x) D_w \psi(x)}.$$

- Define the effective action as

$$S_{\text{eff}}[U] = S_g[U] - \ln \det D_w[U].$$

- We can write the action for full QCD in terms of bosonic fields ϕ using the identity

$$\det M = \frac{1}{\det M^{-1}} = \int \mathcal{D}\phi^\dagger \mathcal{D}\phi e^{-\int d^4x \phi^\dagger(x) M^{-1} \phi(x)}.$$

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Pseudofermions

- The convergence of the Gaussian integral in ϕ is only guaranteed for Hermitian positive definite (Hpd) M .
- For Wilson-type fermions, D_w is a complex matrix, but $\det D_w$ is real and positive.
- So, we can define $M = D_w^\dagger D_w$, and M will be Hpd with $\det M = \det D_w^2$.
- Then the *pseudofermionic* effective action for full QCD with two flavours of degenerate quarks is

$$S_{\text{eff}}[U] = S_g[U] + \int d^4x \phi^\dagger(x) M^{-1}[U] \phi(x).$$

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Hybrid Monte Carlo

- The Hybrid Monte Carlo algorithm creates a Markov chain by alternately performing two steps:
 - A Molecular Dynamics (MD) integration to generate a new configuration ($U \rightarrow U', P \rightarrow P'$).
 - A Metropolis accept/reject step on the proposed configuration (U', P').
- The accept/reject step is based upon the change in the Hamiltonian

$$\rho(U \rightarrow U', P \rightarrow P') \propto e^{-\Delta\mathcal{H}}.$$

- The Molecular Dynamics integration takes place along a trajectory which for sufficiently small integration step sizes $\Delta\tau$ approximately conserves \mathcal{H} , hence yielding high acceptance rates.

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Molecular Dynamics

- Start by requiring that the Hamiltonian be conserved along the trajectory

$$\frac{d\mathcal{H}}{d\tau} = 0.$$

- Then derive the discretised equations of motion,

$$U_\mu(x, \tau + \Delta\tau) = U_\mu(x, \tau) \exp(i\Delta\tau P_\mu(x, \tau)),$$

$$P_\mu(x, \tau + \Delta\tau) = P_\mu(x, \tau) - U_\mu(x, \tau) \frac{\delta S}{\delta U_\mu(x, \tau)}.$$

- The derivative of the action with respect to the gauge fields is known as the *force term*,

$$F_\mu(x) = \frac{\delta S}{\delta U_\mu(x)}.$$

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Splitting The Action

- Lets split our action into its gauge field and pseudofermion field components, $S = S_g + S_{\text{pf}}$, where

$$S_g = \beta \sum_{x, \mu < \nu} \frac{1}{3} \text{Re Tr}(1 - U_{\mu\nu}(x)),$$

$$S_{\text{pf}} = \sum_x \phi^\dagger(x) (D_w^\dagger D_w)^{-1} \phi(x),$$

and D_w is the Wilson fermion matrix.

- Each of the terms in the action induces a force term.
- The size of the force term is the dominant factor in determining what step size $\Delta\tau$ is need for a given acceptance probability ρ_{acc} .
- As the quark mass becomes lighter, the size of the pseudofermion force term increases.

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Leapfrog Integration

- The MD equations of motion induce corresponding time evolution operators,

$$V_T(\Delta\tau) : \{U(\tau), P(\tau)\} \rightarrow \{U(\tau + \Delta\tau), P(\tau)\},$$

$$V_S(\Delta\tau) : \{U(\tau), P(\tau)\} \rightarrow \{U(\tau), P(\tau + \Delta\tau)\}.$$

- The simplest MD integration scheme is the leapfrog

$$V(\Delta\tau) = V_S\left(\frac{\Delta\tau}{2}\right)V_T(\Delta\tau)V_S\left(\frac{\Delta\tau}{2}\right).$$

- MD Integration trajectories typically have unit length, and hence as the step size $\Delta\tau$ decreases, the number of integration steps increases.

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Pseudofermion Force

- Each time we act with $V_S(\Delta\tau)$ we need to evaluate the pseudofermion force term,

$$F_{\text{pf}} = \frac{\delta S_{\text{pf}}}{\delta U}.$$

- This involves inverting the fermion matrix, and hence is expensive!
- However, for split actions $S = S_1 + S_2$ we can use a multiple time scale integration scheme (*nested leapfrog*),

$$V(\Delta\tau) = V_2\left(\frac{\Delta\tau}{2}\right) \left[V_1\left(\frac{\Delta\tau}{m}\right) \right]^m V_2\left(\frac{\Delta\tau}{2}\right),$$

$$V_1(\Delta\tau) = V_{S_1}\left(\frac{\Delta\tau}{2}\right) V_T(\Delta\tau) V_{S_1}\left(\frac{\Delta\tau}{2}\right), \quad V_2 = V_{S_2}(\Delta\tau).$$

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Multiple Time Scales

- Multiple time scale integration is effective when the force term F_1 due to S_1 is cheap to evaluate compared to F_2 (that of S_2).
- However, as the step-size for S_2 is larger, we also require that the size of the force term for S_2 is relatively small compared to that of S_1 .
- The gauge force F_g is cheap compared to the pseudofermion force F_{pf} , and at heavy quark masses $F_g > F_{pf}$, but at light quark masses the UV fluctuations in the pseudo fermion force become too large for multiple time scales to be effective.
- This is where polynomial filtering steps in.

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Polynomial Filtering

- We can use a polynomial filter $\mathcal{P} = \mathcal{P}(M)$ to separate the ultraviolet and infrared physics in the pseudofermion force,

$$S_{\text{poly}} = \chi^\dagger \mathcal{P} \chi,$$

$$S_{\text{pf}} = \phi^\dagger (M\mathcal{P})^{-1} \phi.$$

- Recall $M = D_w^\dagger D_w$ is Hermitian positive definite.
- As S_{poly} is fast to evaluate compared to S_{pf} we split the action in the following way,

$$S_1 = S_g + S_{\text{poly}}, \quad S_2 = S_{\text{pf}}.$$

- If $\mathcal{P} \approx 1/z$ then it will capture the short-distance physics in S_{poly} and act as a UV filter in S_{pf} .

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- Recall $M = D_w^\dagger D_w$ is Hermitian positive definite.
- As S_{poly} is fast to evaluate compared to S_{pf} we split the action in the following way,

$$S_1 = S_g + S_{\text{poly}}, \quad S_2 = S_{\text{pf}}.$$

- If $\mathcal{P} \approx 1/z$ then it will capture the short-distance physics in S_{poly} and act as a UV filter in S_{pf} .

Fermionic Determinant

- Note that the fermionic determinant is unchanged by the introduction of the polynomial filter.
- To see this we note that

$$\begin{aligned} & \int \mathcal{D}\phi^\dagger \mathcal{D}\phi \mathcal{D}\chi^\dagger \mathcal{D}\chi e^{-\int d^4x \chi^\dagger \mathcal{P} \chi + \phi^\dagger(x)(M\mathcal{P})^{-1}\phi(x)} \\ &= \frac{\det \mathcal{P}}{\det(M\mathcal{P})} = \frac{1}{\det M^{-1}} = \det M \end{aligned}$$

- In the limit as the order of the polynomial $n \rightarrow \infty$ we have $M\mathcal{P} \rightarrow 1$ and $\mathcal{P}(M) \rightarrow M^{-1}$.
- In this way the polynomial term can reproduce as much or as little of the pseudofermion term as we want.

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Chebyshev Filter

- An effective UV filter is the n^{th} order Hermitian Chebyshev polynomial approximation to $1/z$,

$$\mathcal{P}_n(z) = a_n \prod_{k=1}^n (z - z_k) \approx \frac{1}{z},$$

where we set $\theta_k = \frac{2\pi k}{n+1}$ to obtain the roots

$$z_k = \lambda \left[\frac{1}{2} (1 + \epsilon) (1 - \cos \theta_k) - i\sqrt{\epsilon} \sin \theta_k \right].$$

- The normalisation is defined by $z_0 = \frac{1}{2}(1 + \epsilon)$, with

$$a_n = \frac{1}{z_0 \prod_{k=1}^n (z_0 - z_k)}.$$

- The approximation is good between $[\epsilon, 1]$, so we rescale with

$$\lambda = 1 + 8\kappa.$$

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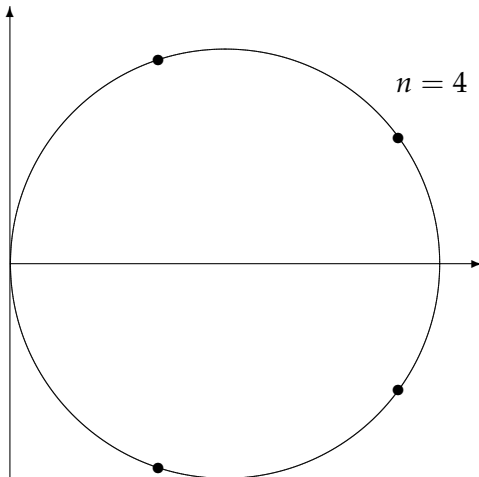
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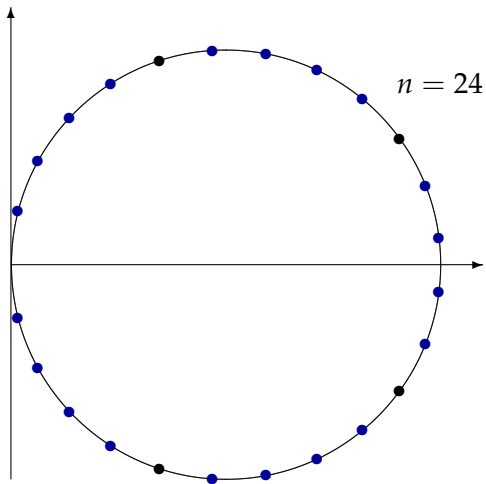
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Chebyshev Roots



Chebyshev Roots



Intermediate Filter

- Using this property of the Chebyshev polynomials, we can add an intermediate filter to our action as a bridge between the high and low energy scales, e.g.

$$S_1 = S_g \quad S_2 = \chi^\dagger \mathcal{P}_m \chi,$$
$$S_3 = \chi^\dagger \mathcal{P}_{m|n} \chi, \quad S_4 = \phi^\dagger (M \mathcal{P}_n)^{-1} \phi.$$

- \mathcal{P}_n denotes the Chebyshev polynomial of order n .
- $\mathcal{P}_{m|n}$ is defined so that $\mathcal{P}_n = \mathcal{P}_m \mathcal{P}_{m|n}$.
- This allows us to perform fermion matrix inversions even less frequently.
- This may(?) be more efficient than a single filter algorithm.
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Integration Scheme

- With a second filter, we have four different scales, five (or more) if we are doing a 2+1 flavour simulation.
- Nested leapfrog is too cumbersome for fine tuning these scales.
- We make use of the fact that $V_i = V_{S_i}$ all commute to introduce a generalised integration scheme.
- If N_i is the number of integration steps per trajectory, then nested leapfrog requires

$$N_i | N_{i-1} \forall i$$

- The new integration scheme requires only that

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Generalised Leapfrog

- Set $N = N_1$ and set $n_i = N_1/N_i$
- The generalised leapfrog algorithm is then:
 - ① Perform an initial half-step $V_i(\frac{1}{2}\Delta\tau_i)$ updating P for all i .
 - ② Loop over $j = 1$ to $N - 1$
 - * Apply $V_T(\Delta\tau)$ to update U .
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 - ④ Perform a final half-step $V_i(\frac{1}{2}\Delta\tau_i)$ updating P for all i .
- Can show using BCH that it has errors of $\mathcal{O}[(\Delta\tau)^3]$.
- Reduces to nested leapfrog for $N_i|N_{i-1}$.

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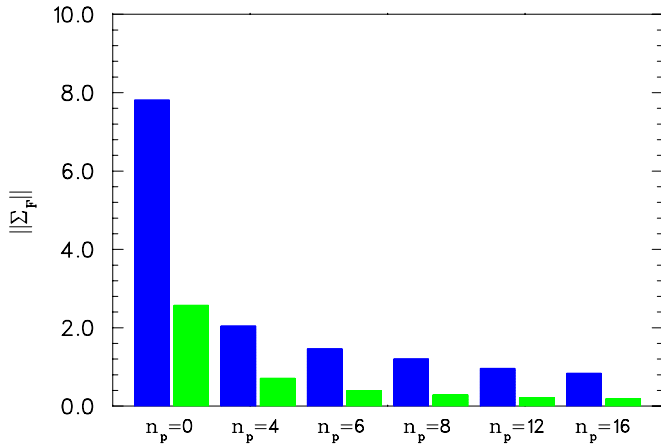
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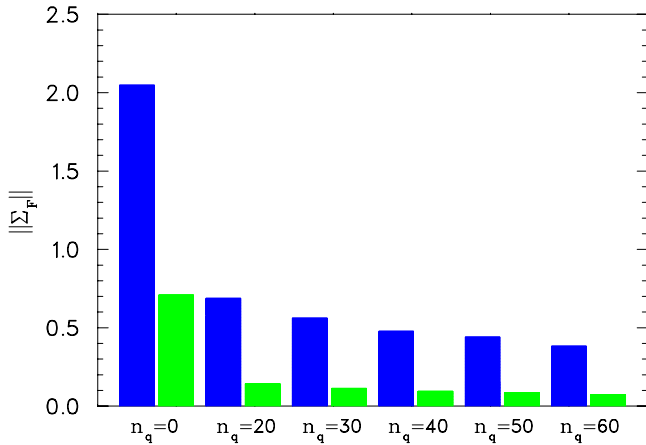
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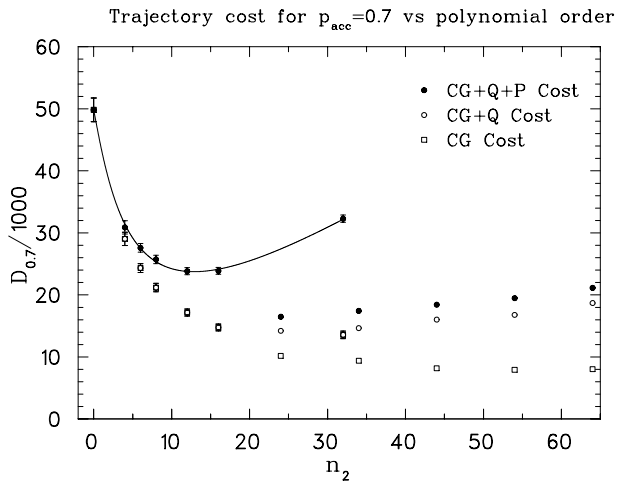
Pseudofermion force vs n_p



Pseudofermion force vs n_q , with $n_p = 4$

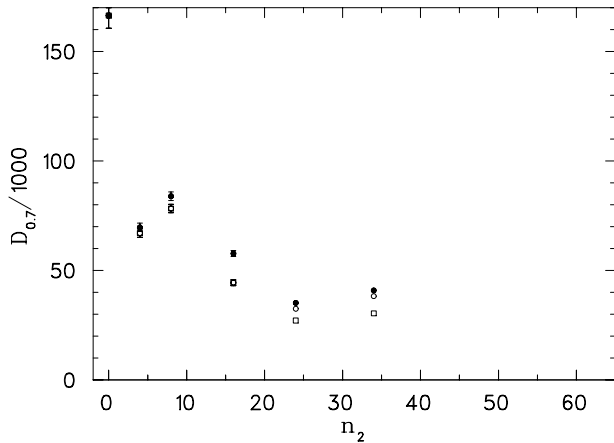


Results $\kappa = 0.1575, m_\pi = 665\text{MeV}$



Results $\kappa = 0.15825, m_\pi \approx 400\text{MeV}$

Trajectory cost for $p_{\text{acc}}=0.7$ vs polynomial order



Single Flavour QCD

- Single fermion flavours can be simulated using a rational polynomial,

$$\mathcal{R}(M) = \sum \frac{a_i}{M + b_i} \approx \frac{1}{\sqrt{M}}$$

(or some other method e.g. polynomial approx. to $1/\sqrt{M}$).

- Recall $M = D_w^\dagger D_w$ is Hermitian positive definite.
- Can we extend our polynomial filtering technique to single flavour simulations?
- Suppose we have a polynomial Q such that

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- E.g. numerically calculate coefficients for Chebyshev approximation to $1/\sqrt{z}$, then calculate the roots...

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- Then we can write

$$S_{\text{poly1f}} = \chi_{1f}^\dagger Q \chi_{1f},$$

$$S_{\text{1pf}} = \phi_{1f}^\dagger \mathcal{R} Q^{-1} \phi_{1f}.$$

- As before, the determinant is unaffected by the addition of the polynomial filter.
- Could add an intermediate filter for the single flavour as before but at the strange quark mass probably not worth it.
- Knowing roots of Q is needed to rewrite $\mathcal{R} Q^{-1}$ as a sum over poles.
- This allows the use of efficient linear multi-shift system solvers.

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- Then we can write

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Alternative Approximation

- Note that $\mathcal{R}Q^{-1} \approx 1$.
- May be advantageous to simply use the Remes algorithm to get a rational approximation to

$$\tilde{\mathcal{R}}(z) \approx f(z) = \frac{1}{\sqrt{z}Q(z)}$$

and use that instead of the product $\mathcal{R}Q^{-1}$.

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- The rational approximation to f might have improved precision for a given order.
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Another Variant

- Recall that we used the Hermitian Chebyshev approximation to $1/z$ in our two flavour polynomial filter.
- The non-Hermitian Chebyshev approximation $\mathcal{K}(z)$ to $1/z$ has the same normalisation, but slightly different roots,

$$y_k = d(1 - \cos \theta_k) + i\sqrt{d^2 - c^2} \sin \theta_k.$$

- Valid for an elliptical region in the complex plane.
- So long as the spectrum of the non-Hermitian matrix D_w is within this ellipse, we can write

$$\mathcal{K}(D_w) = a_n \prod_{k=1}^{n/2} (D_w - y_k)(D_w - y_k^*) \approx \frac{1}{D_w}$$

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Factoring the Polynomial

- Now construct a polynomial using only half the roots (say those with positive imaginary parts),

$$\mathcal{K}_+(D_w) = \sqrt{a_n} \prod_{k=1}^{n/2} (D_w - y_k)$$

- We need the following two properties of determinants,

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The Action

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- Here, \mathcal{W} needs to be a rational polynomial approximation to $\{z\mathcal{K}_+^*(z)\mathcal{K}_+(z)\}^{-1}$.
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- In combination with a generalise leapfrog algorithm we successfully reduce the cost of dynamical simulations.
- The generalised leapfrog algorithm is applicable to any multiple time scale integration scheme, far more flexible than nested leapfrog.
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