

Lidar at Adelaide

CTA Workshop, 30 Sept 2013

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Coherent Lidar

Water Vapour DIAL

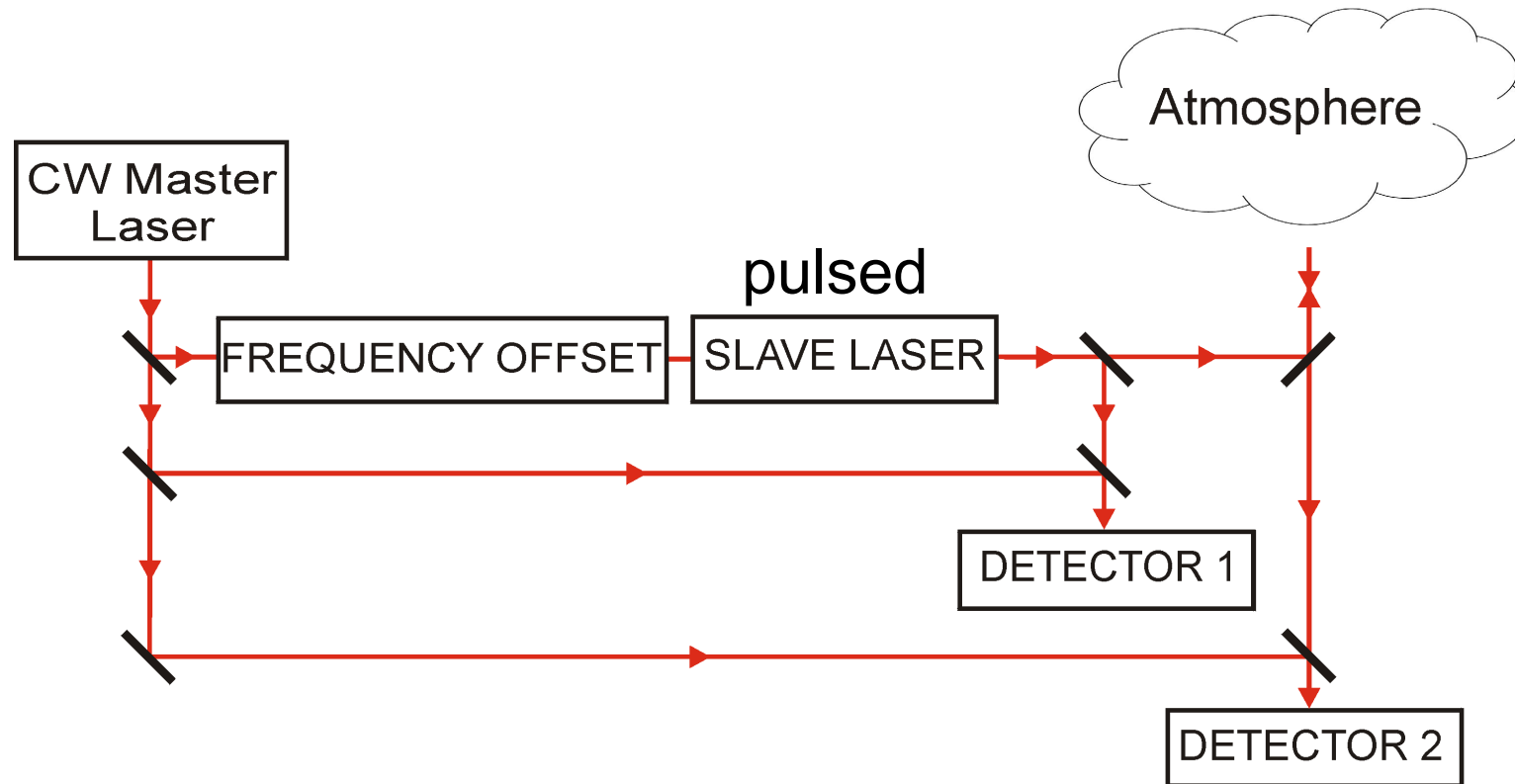
Rayleigh/Raman/Fe-Boltzmann Lidar

Na Guide-Star Laser

People

Nick Chang, Myles Clark, Alex Dinovitser, Murray Hamilton,
Lachlan Harris, Matthew Heintze, David Hosken, Andrew
MacKinnon, Jesper Munch, David Ottaway, Iain Reid, Tom Rutten,
Nikita Simakov, Liam Twigger, Peter Veitch, Bob Vincent, ...

Coherent Laser Radar System



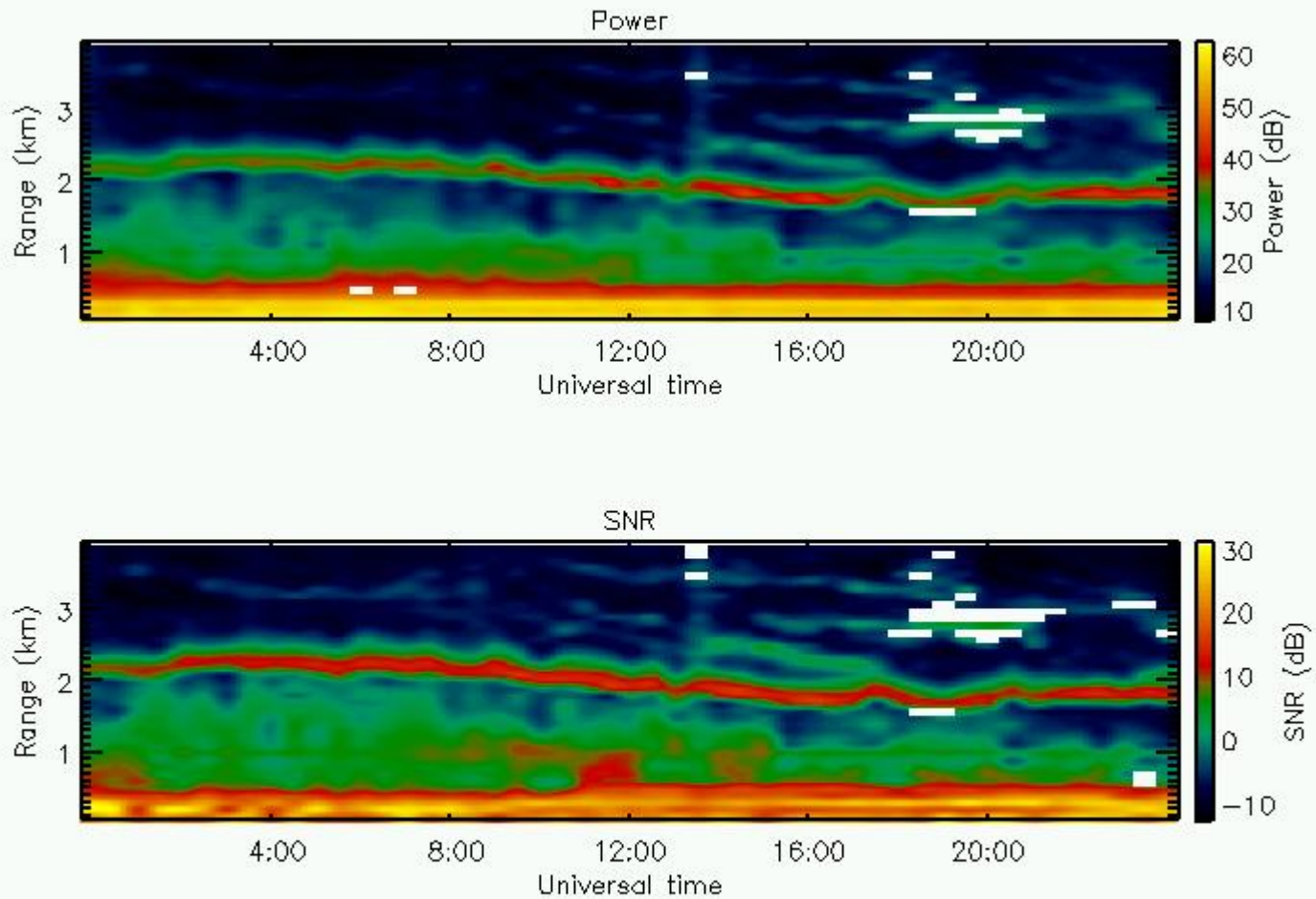
Initially: diode-pumped Er:Yb:glass (0.5 mJ, 2 Hz, 1535 nm)

Now: diode-pumped Er:YAG (10-20 mJ, 1 kHz, 1645 nm)

An example of a wind-speed measurement

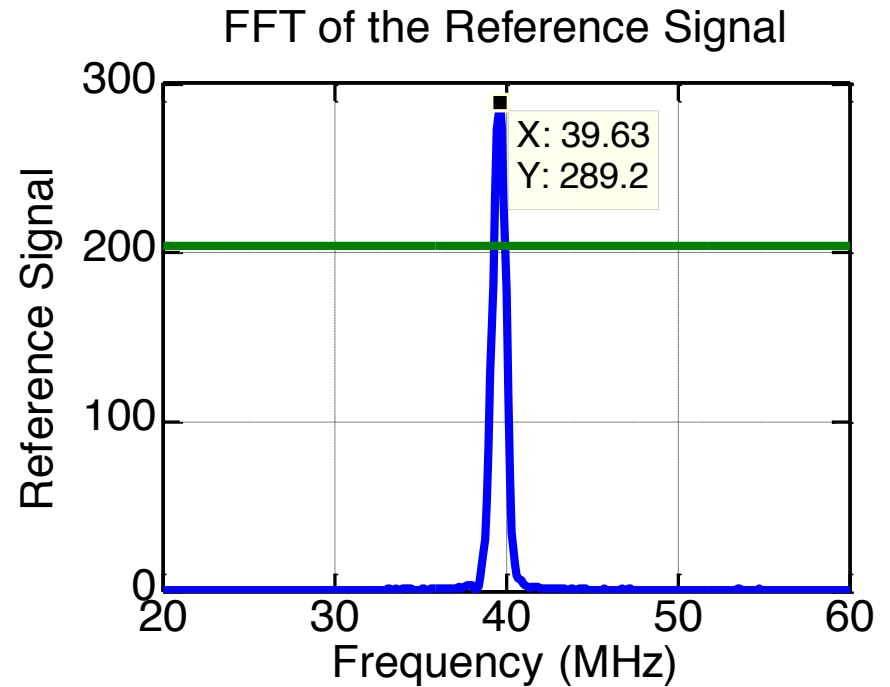
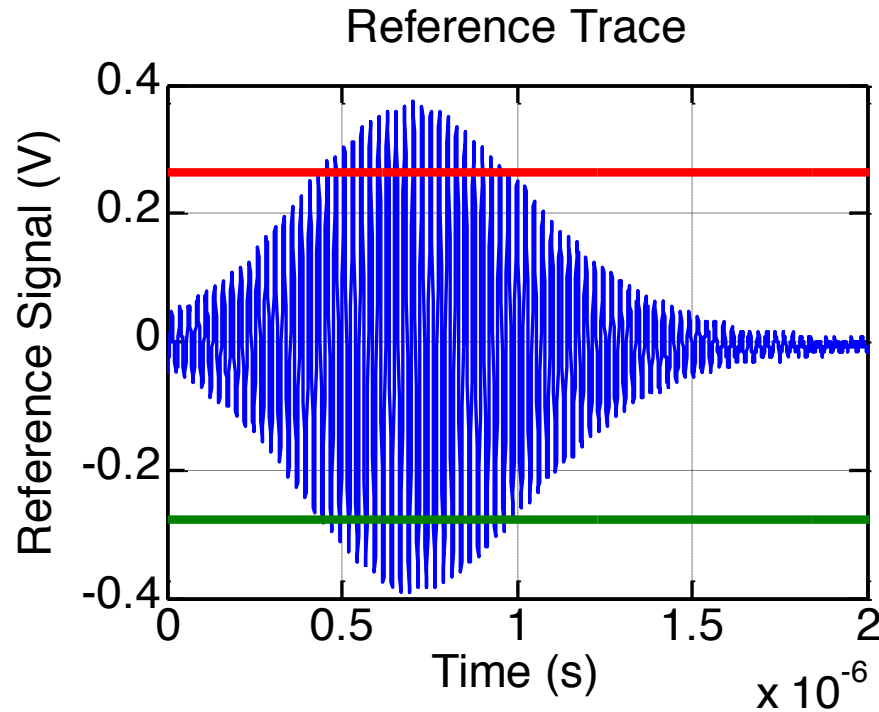
- Er:Yb:glass slave laser
- Pulse energy: 0.5 mJ
- Direction: 12° from zenith
- 500-sample range gates (500 ns duration, 75% overlap)
- 3500 sample zero padding → 0.25 MHz bins
- Single shot (no averaging)
- Spectra for range gates in which no signal usually not shown
- Statistically significant peaks in spectra are labeled

Adelaide Airport Boundary Layer Radar



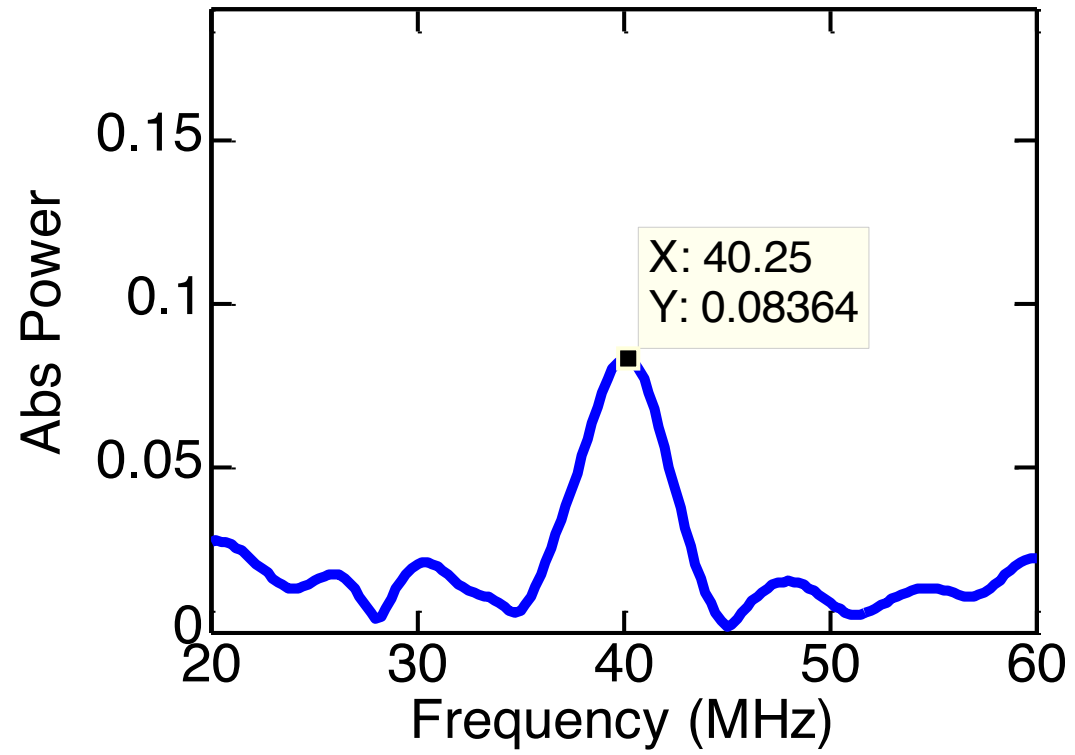
20090210_aap_fca.fca: 10/02/2009 00:00:51 to 23:59:10

Reference pulse

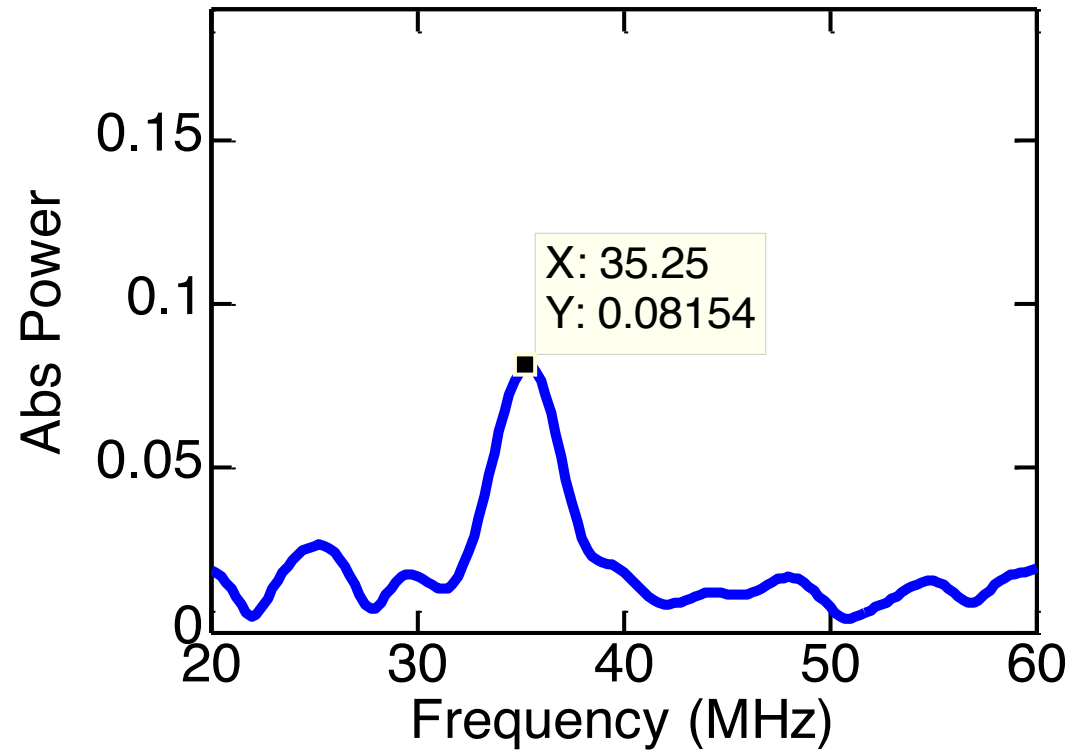


Pulse duration ~ 500 ns \rightarrow range resolution ~ 75 m

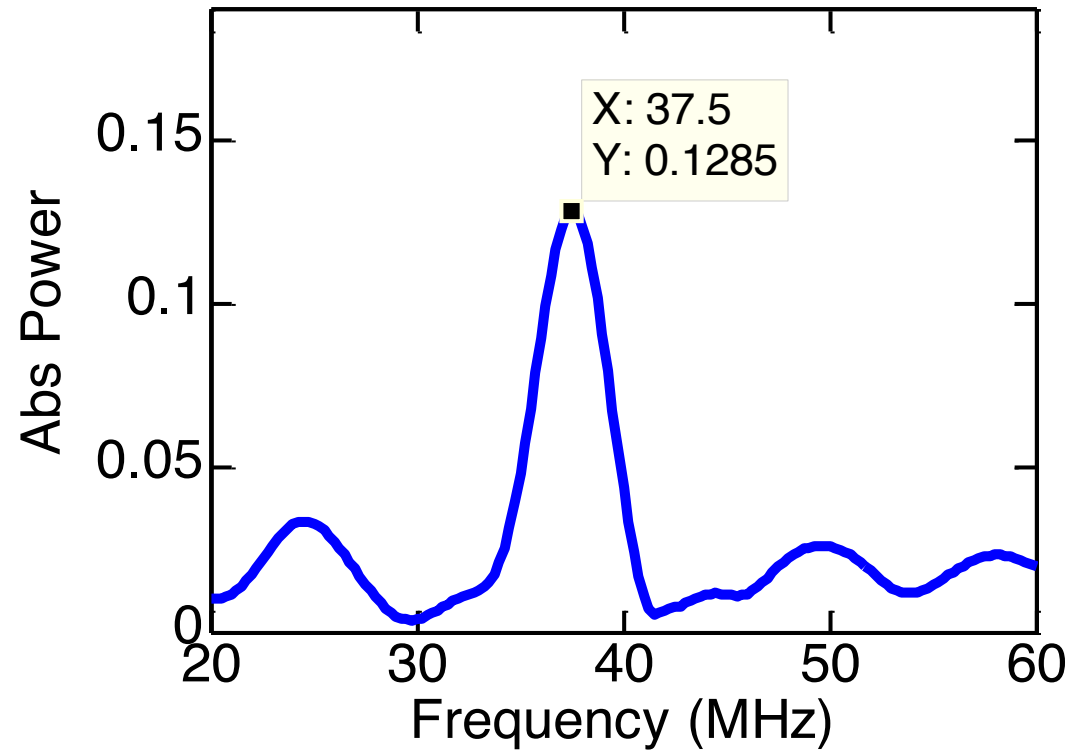
Height of gate = 215.225m



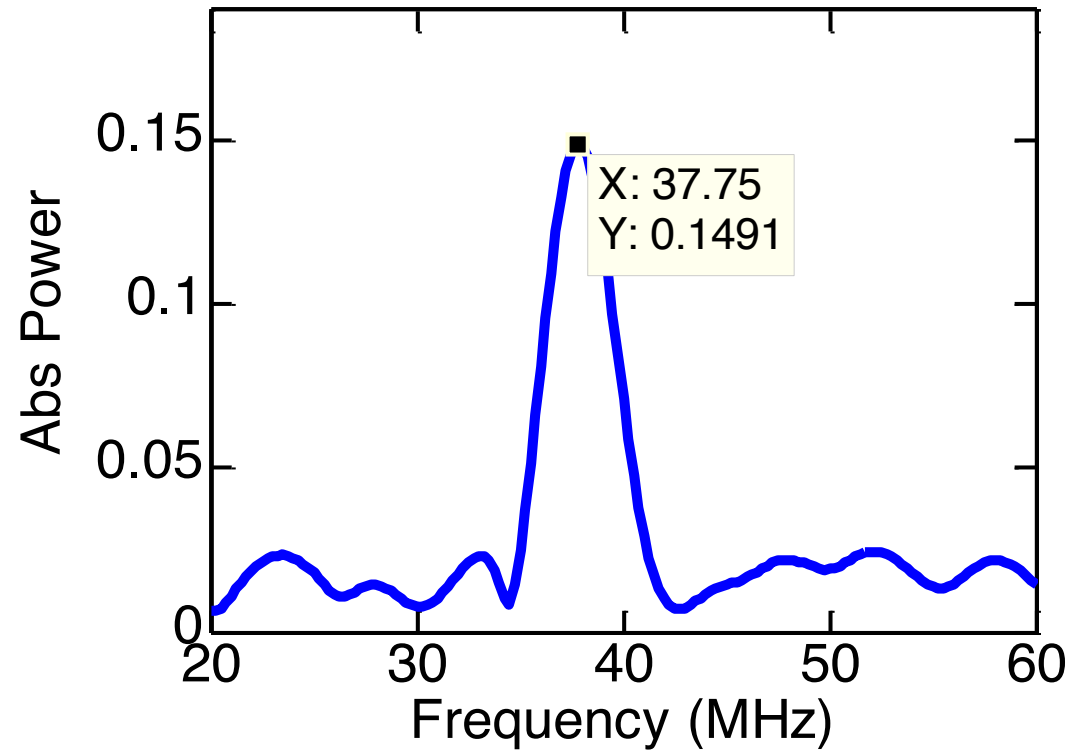
Height of gate = 608.975m



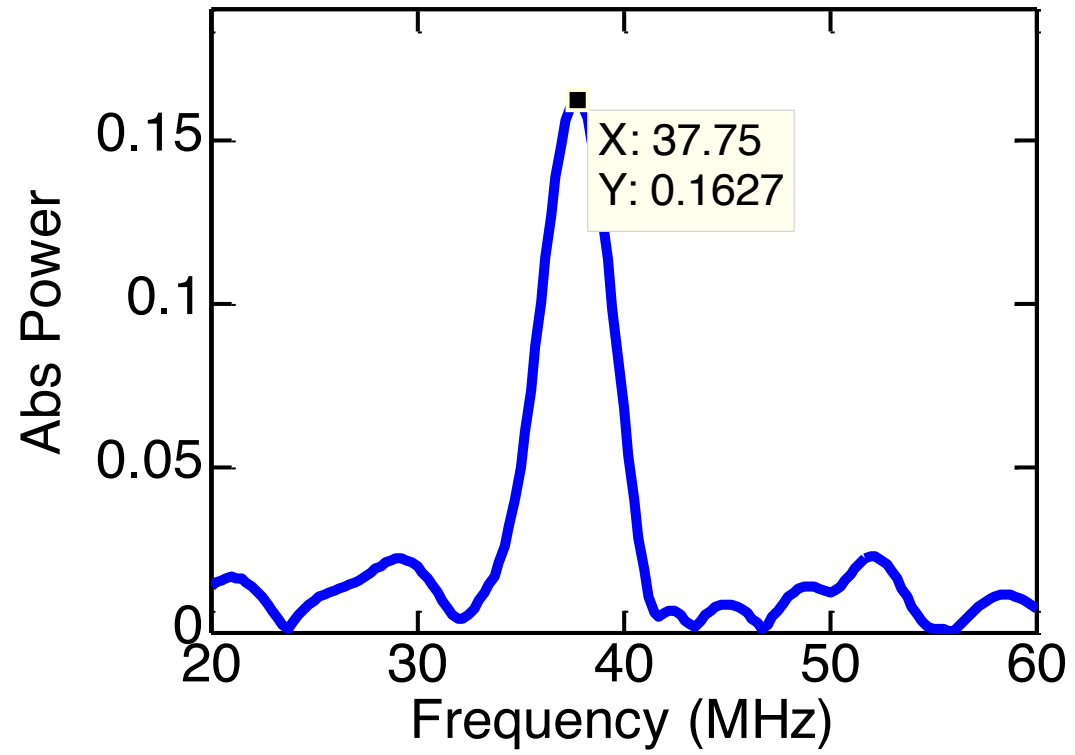
Height of gate = 1996.475m



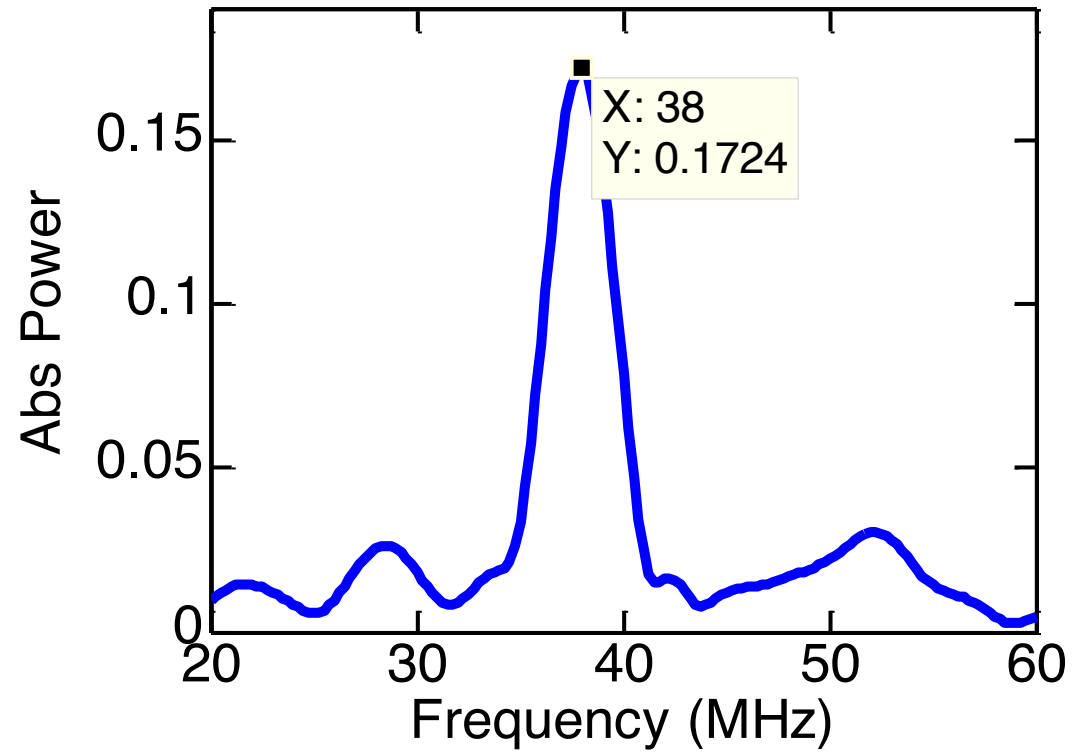
Height of gate = 2015.225m



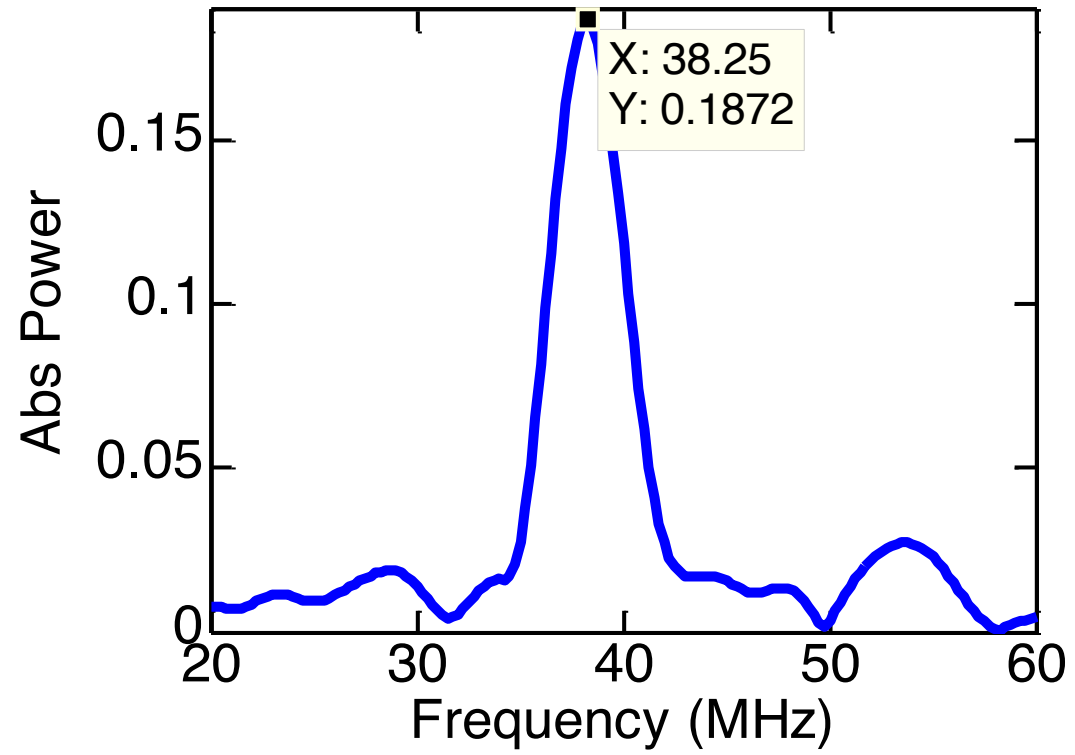
Height of gate = 2033.975m



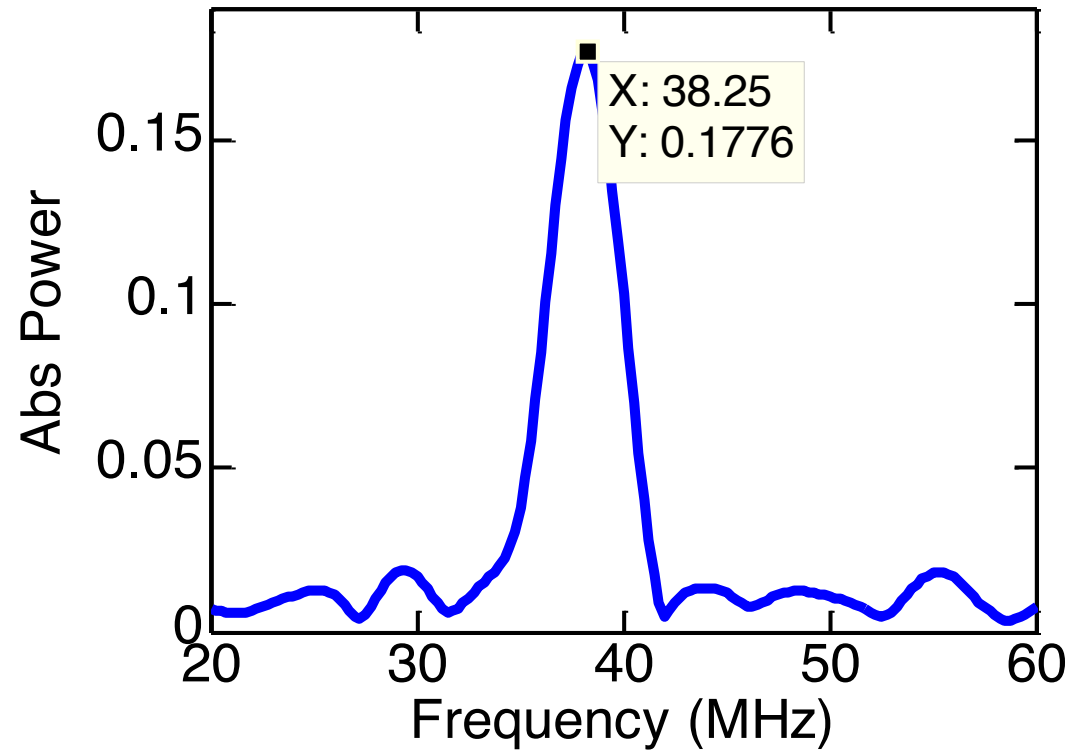
Height of gate = 2052.725m



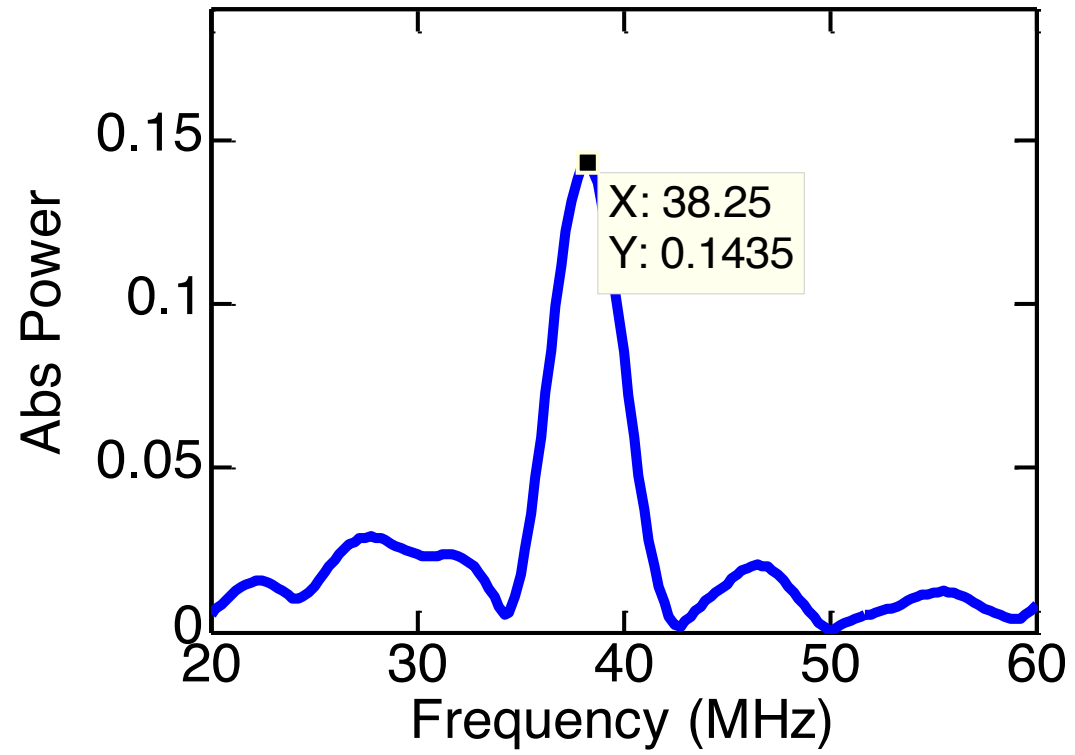
Height of gate = 2071.475m



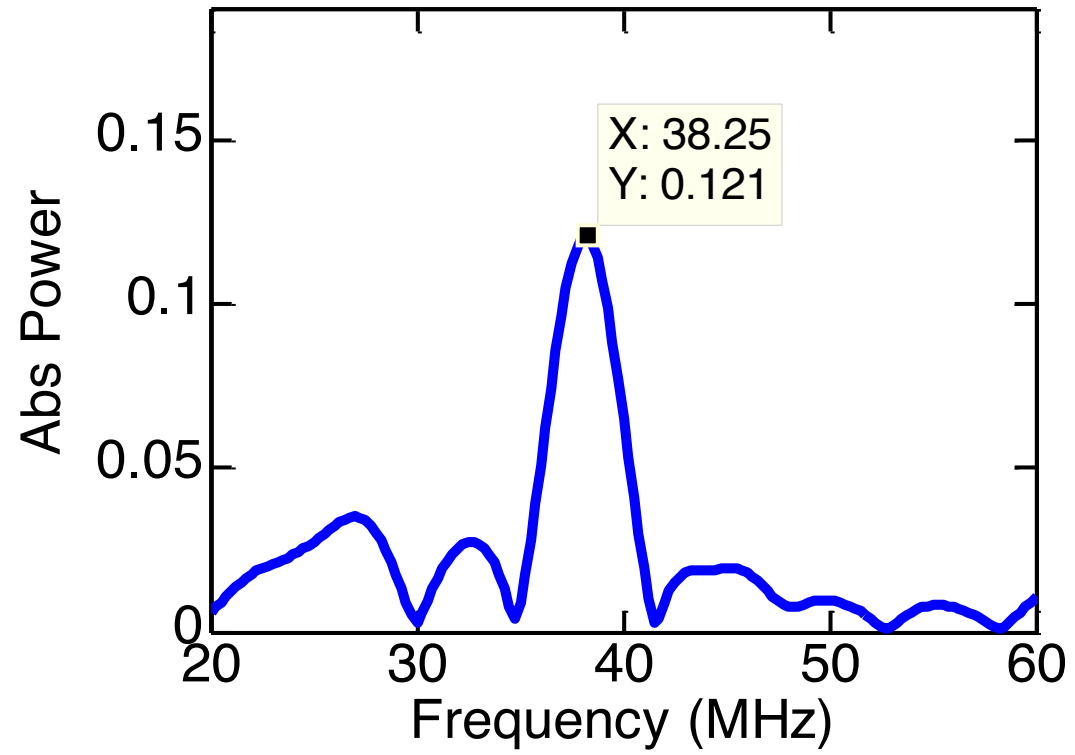
Height of gate = 2090.225m



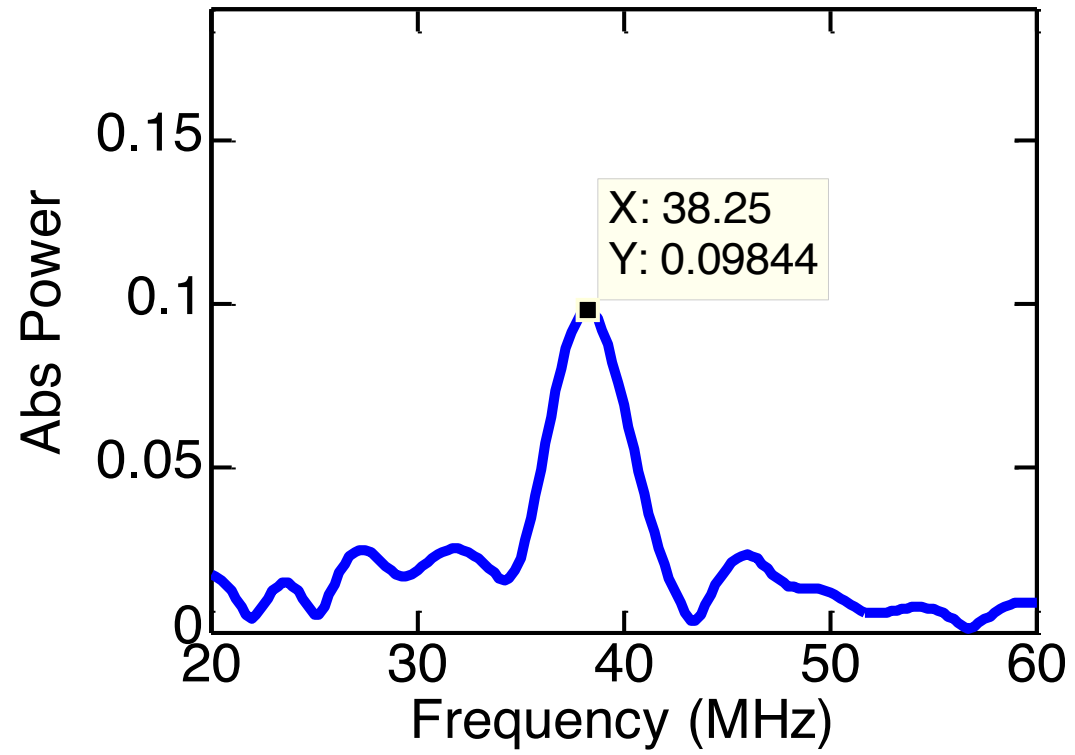
Height of gate = 2108.975m

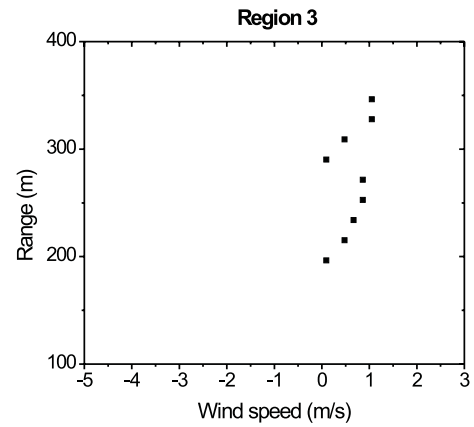
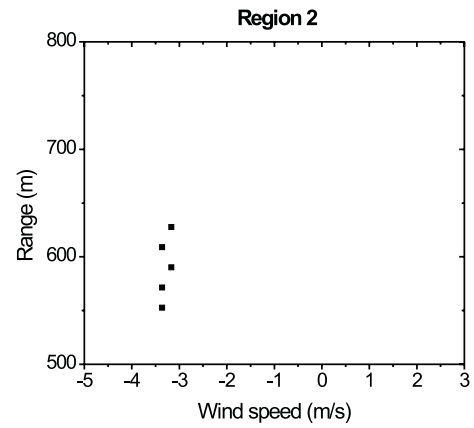
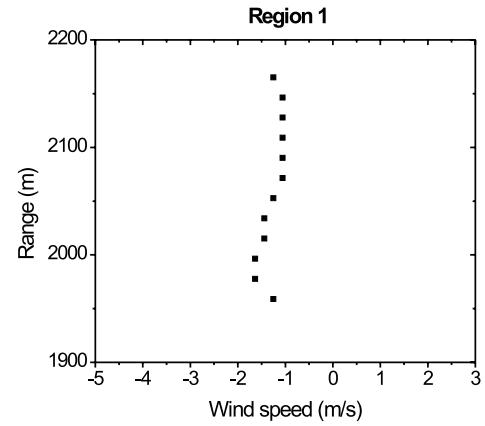


Height of gate = 2127.725m



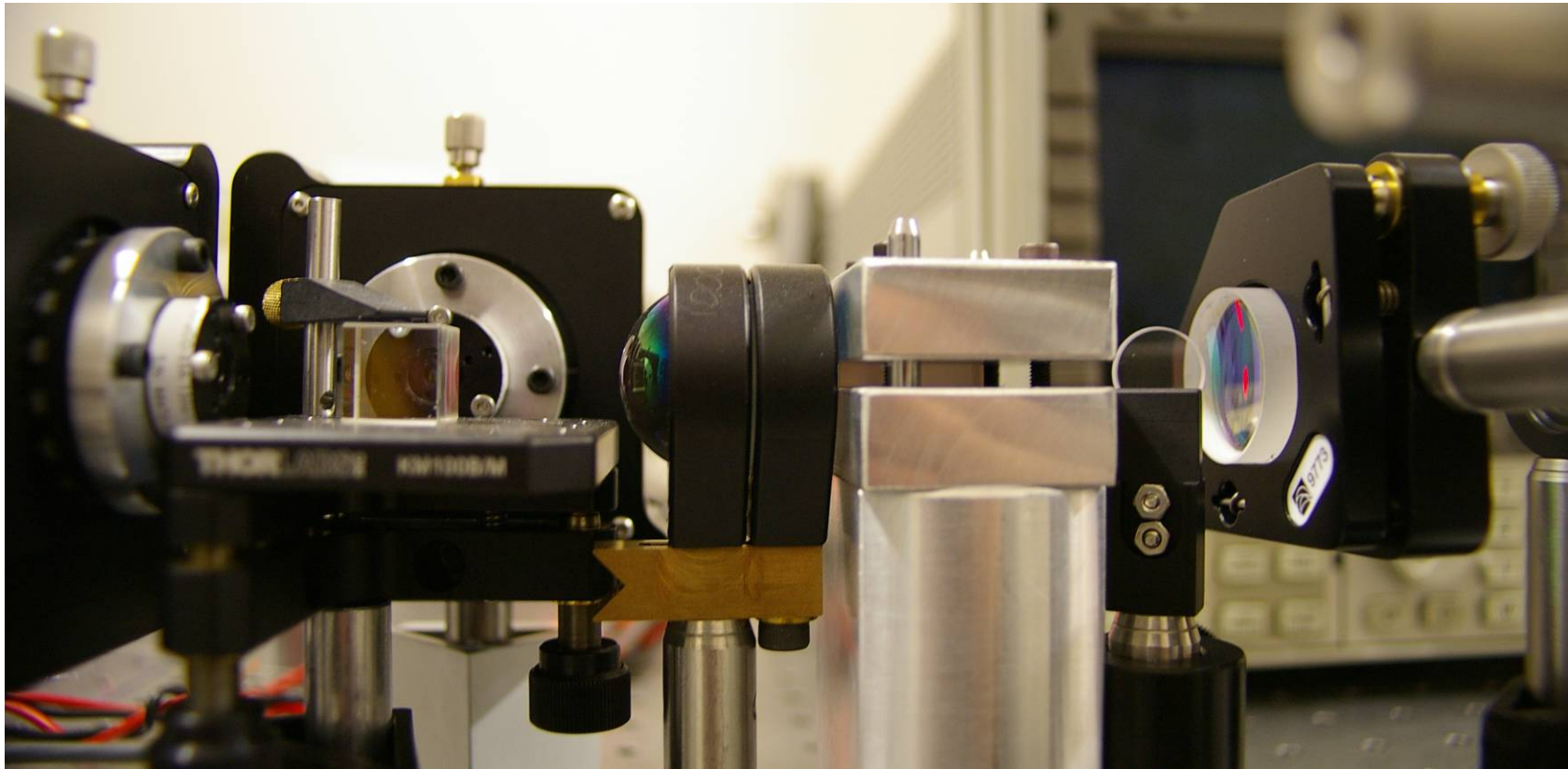
Height of gate = 2146.475m



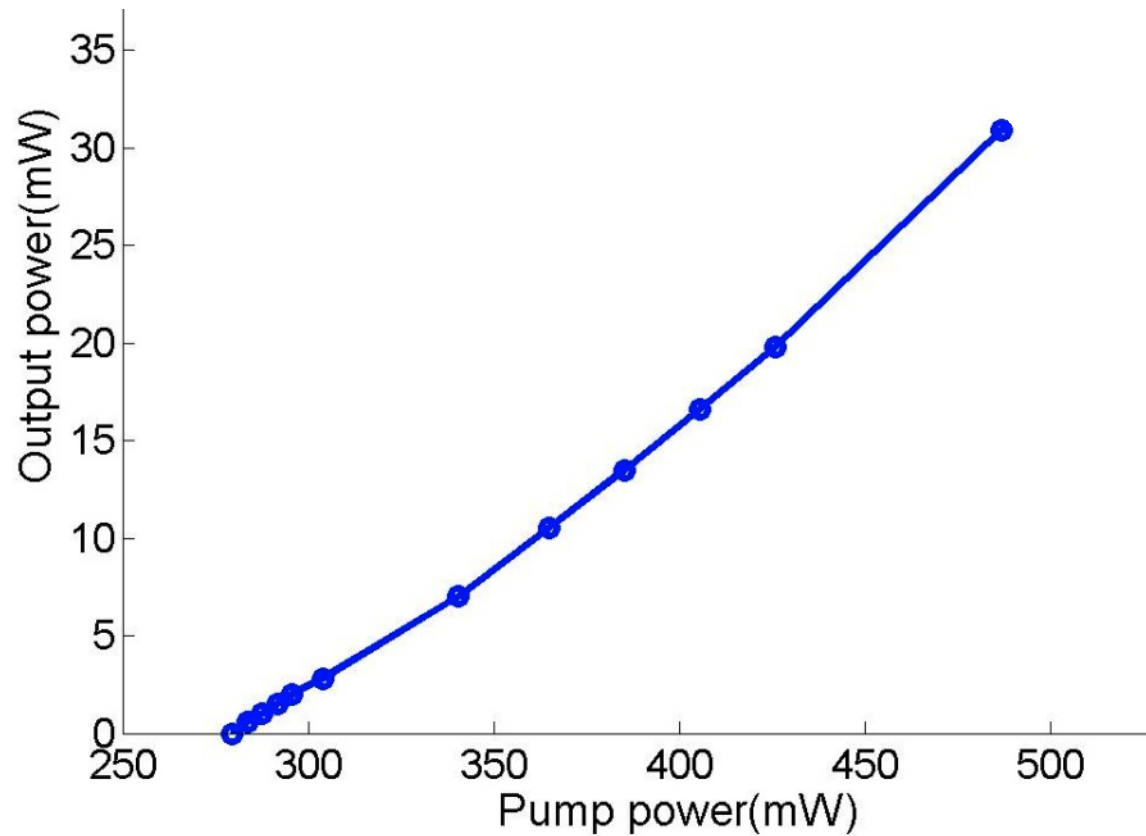


Upper limit for instrument-limited
shot-to-shot reproducibility: 0.4 ms^{-1}

Er:YAG master laser

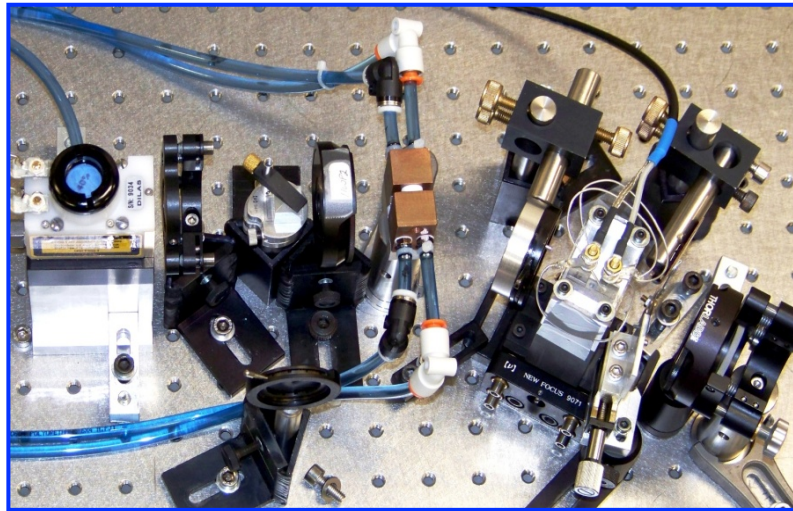


Single frequency, polarized output at 1645nm

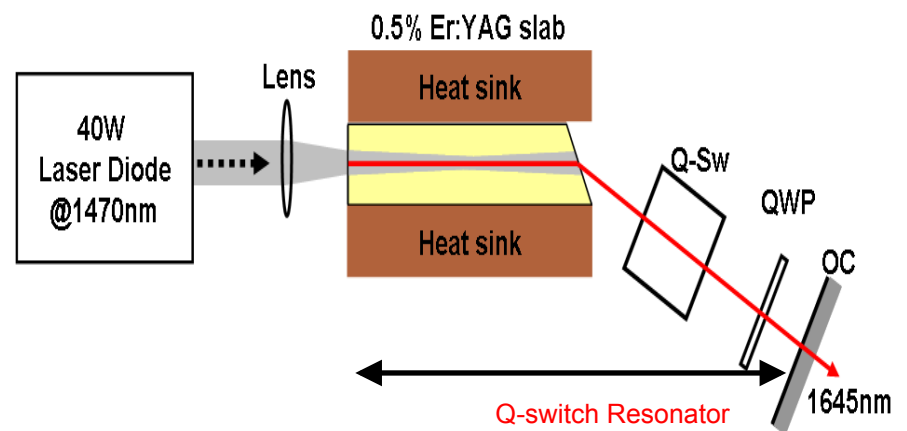


line-width < 12 kHz

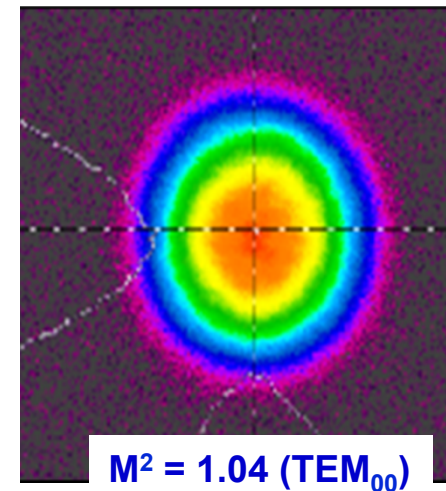
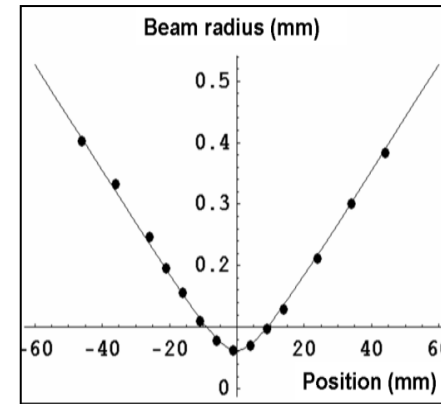
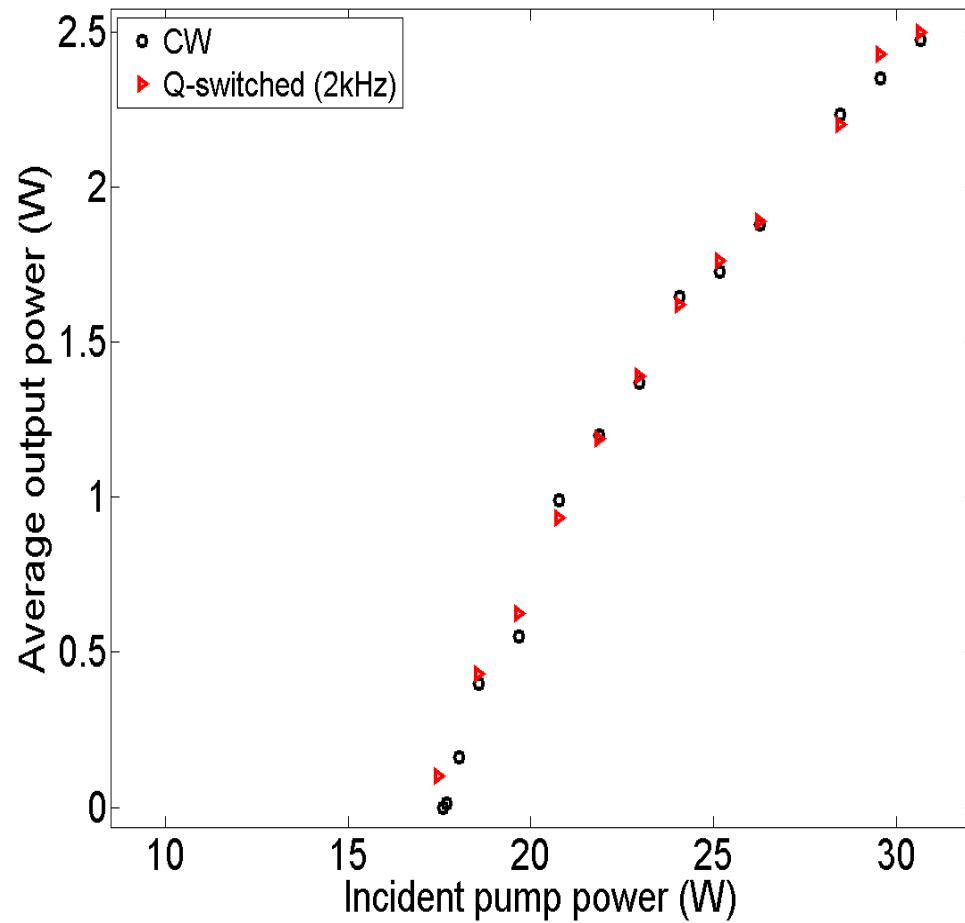
Initial pulsed Er:YAG laser



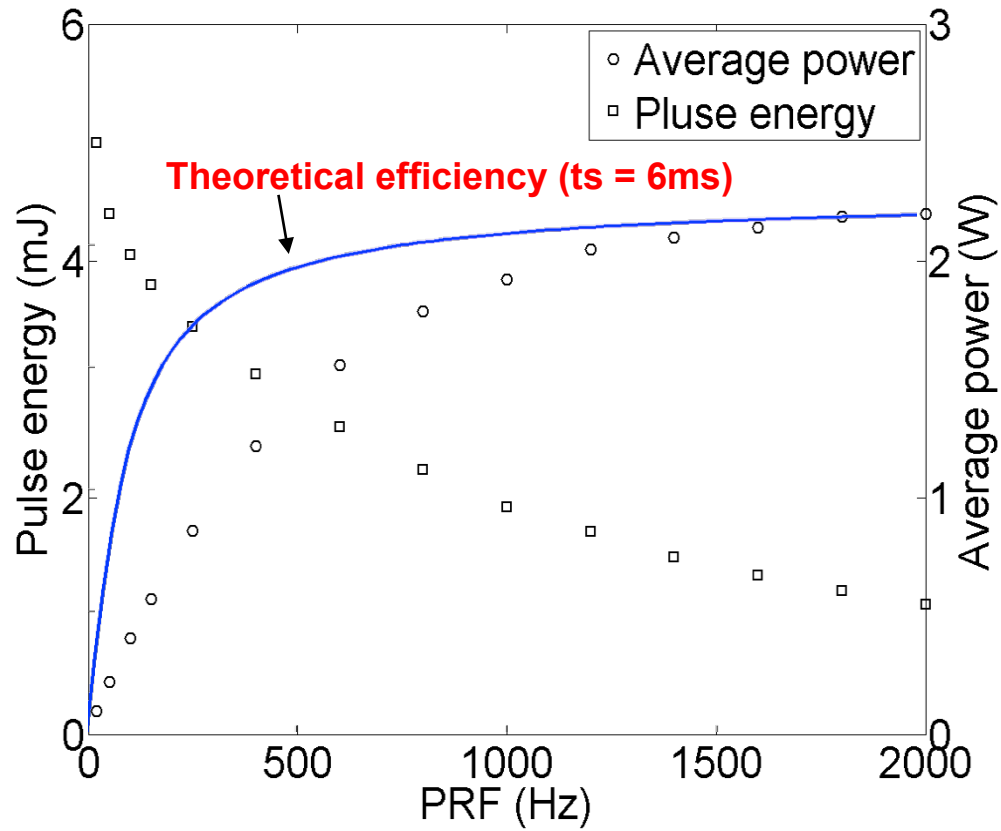
Length = ~30cm



Output of pulsed Er:YAG laser



Output v's PRF



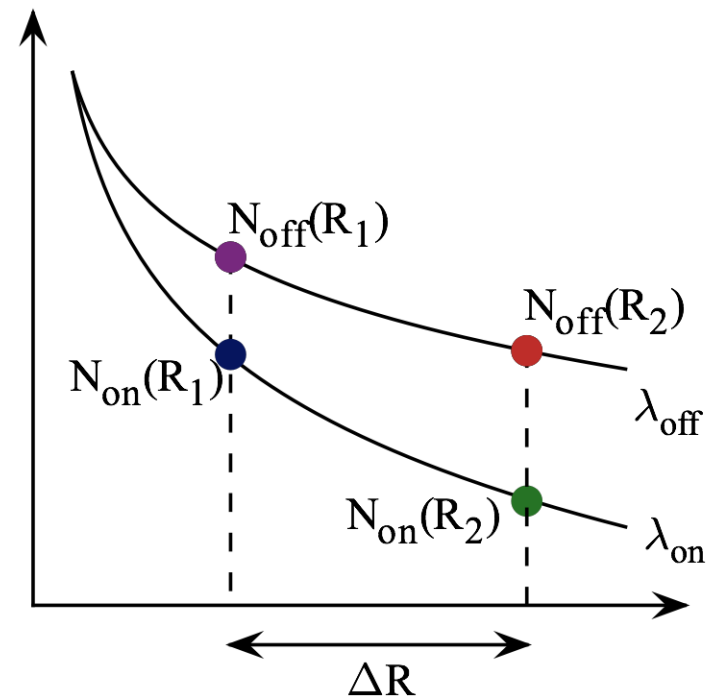
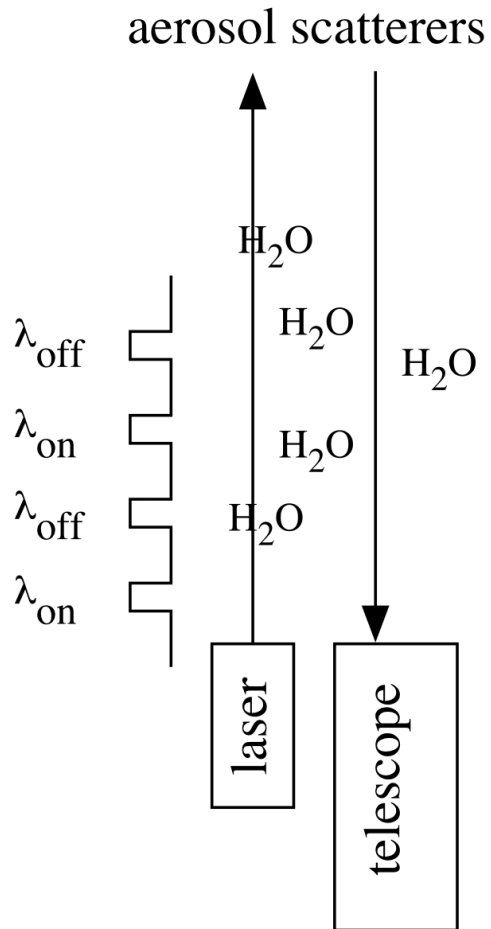
Output coupler, R = 85%

Next for Coherent Lidar?

- Change gain medium to end-pumped CPFS gain
- Use cheaper FAC 1470 nm pump diodes
- Increase output to 10-20 mJ @ 1 kHz PRF
- Incorporate in static (then scanning) coherent lidar system

Low-cost water-vapour DIAL

DIAL principle



Water vapour concentration between R_1 and R_2 :

$$n_{H_2O} = \frac{1}{2\Delta R(\sigma_{on} - \sigma_{off})} \ln \left[\frac{N_{on}(R_1)N_{off}(R_2)}{N_{on}(R_2)N_{off}(R_1)} \right]$$

Low cost DIAL - laser considerations

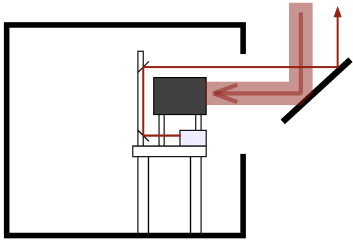
Diode laser is only really low cost laser available, but need a semiconductor optical amplifier!

Choice of wavelength

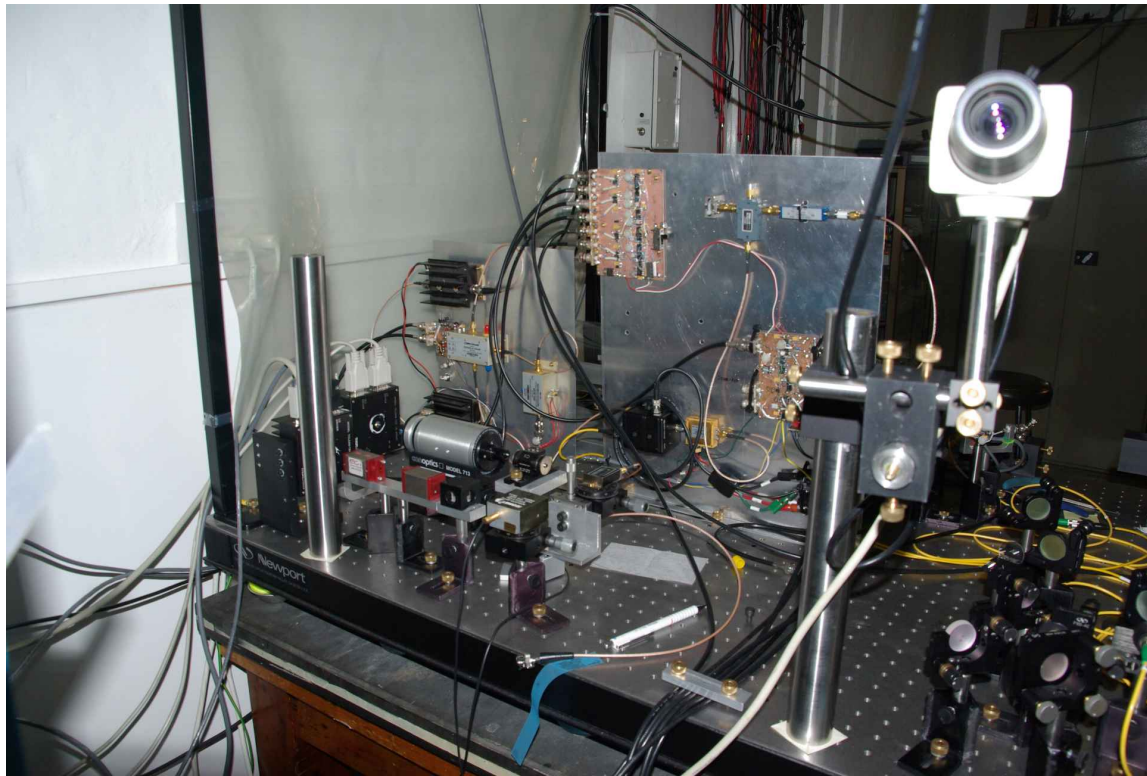
- 830 nm GaAs (mature technology)
- Single mode limited to ~ 0.5 W (high power diode or optical amplifier)
 - Implies single photon counting
- Detector technology well developed (PMT or Si PIN/APD)

Type of diode?

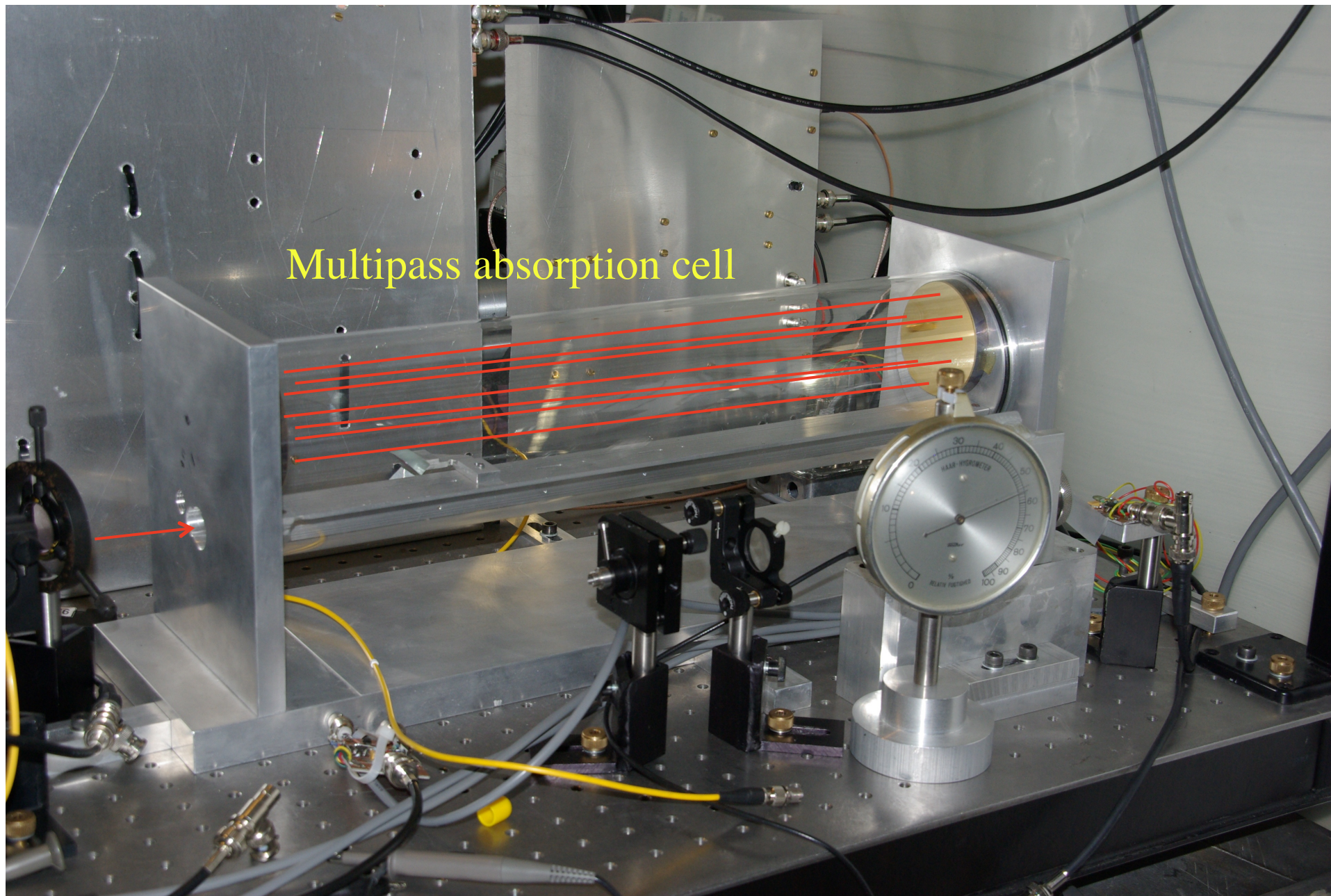
- Use FP diode (for better or for worse)
- DFB diode (NOAA, Machol et al.)
- External cavity (MSU, see Nehrir et al. ISTP8 S13-P08)



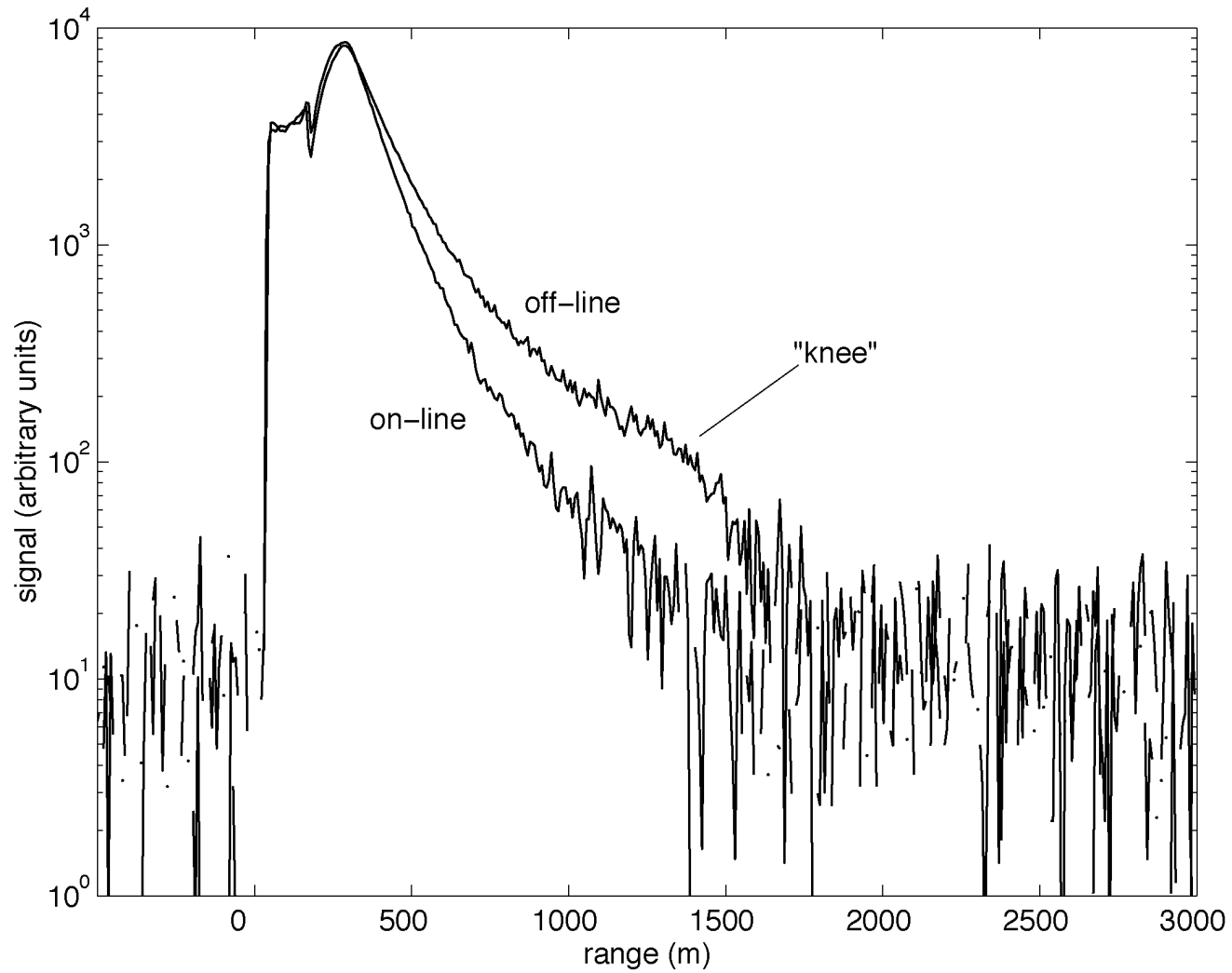
DIAL Hardware



Multipass absorption cell



Raw DIAL Return Signals

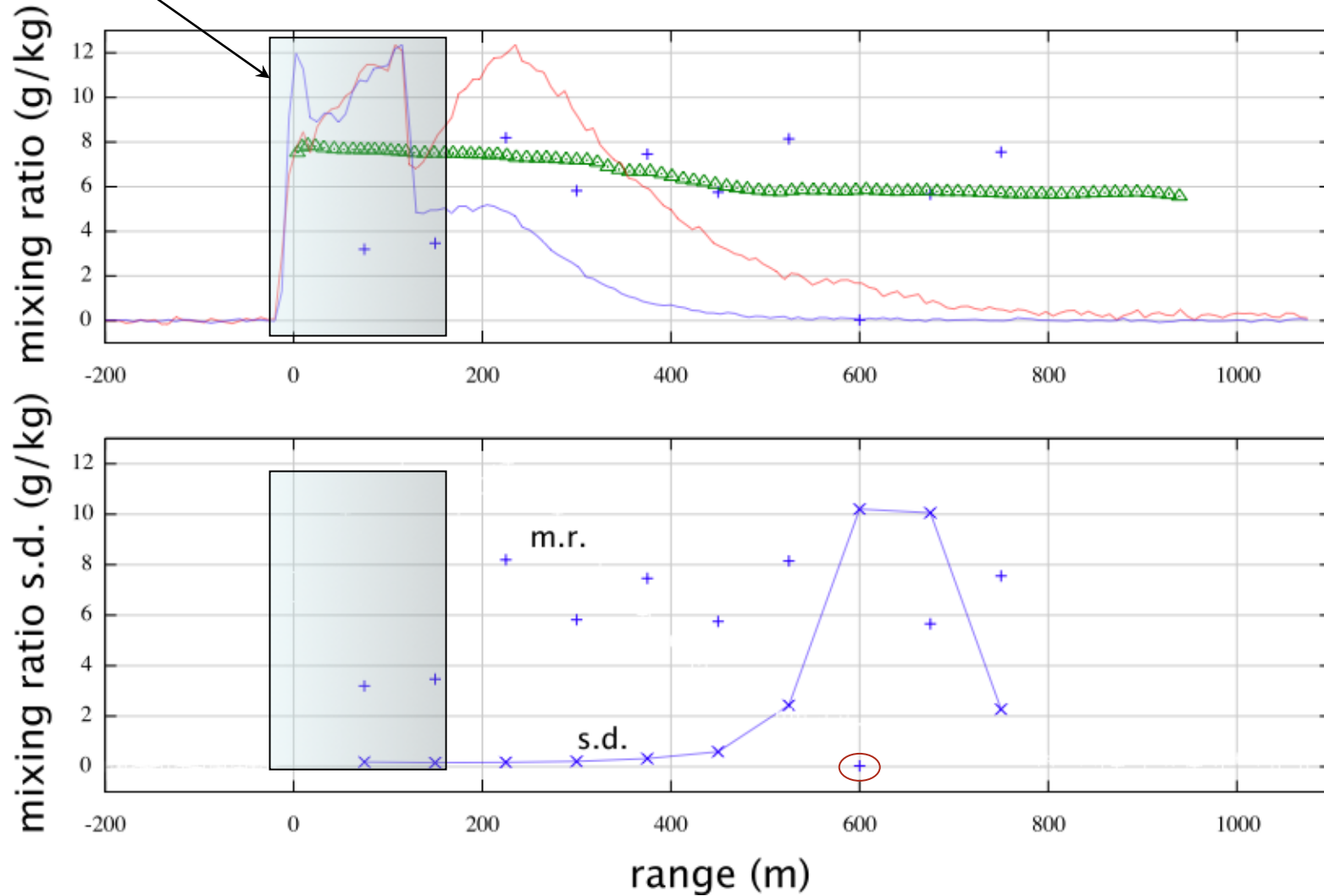


822.922 nm absorption line used is better suited to very dry environments.

Inversion of raw DIAL data 23/9/09 - blue plus signs
BoM sonde data - green triangles
standard dev' n below

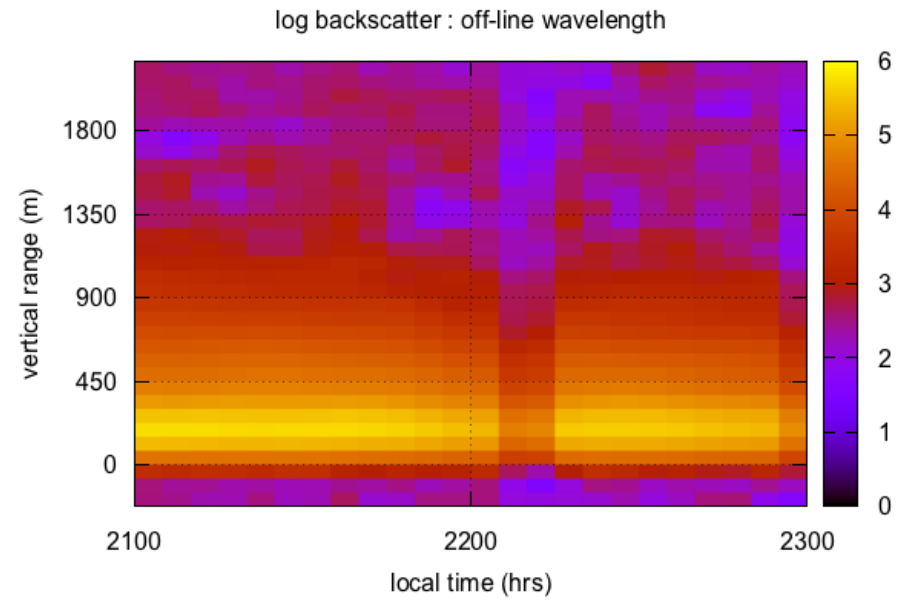
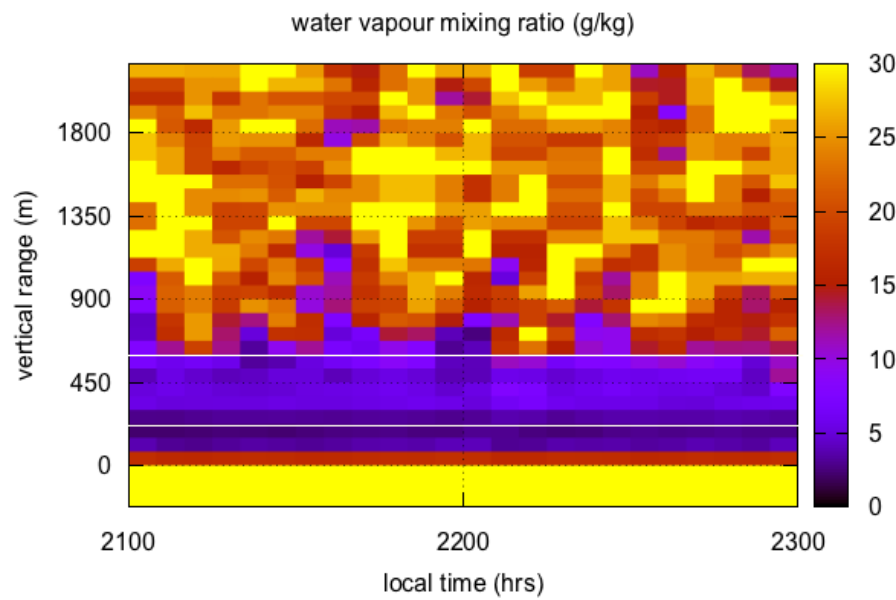
45° mirror signal

water mixing ratios, 23/09/09 1137 UT to 1152 UT



DIAL RESULTS

- Adelaide 22 03 2010



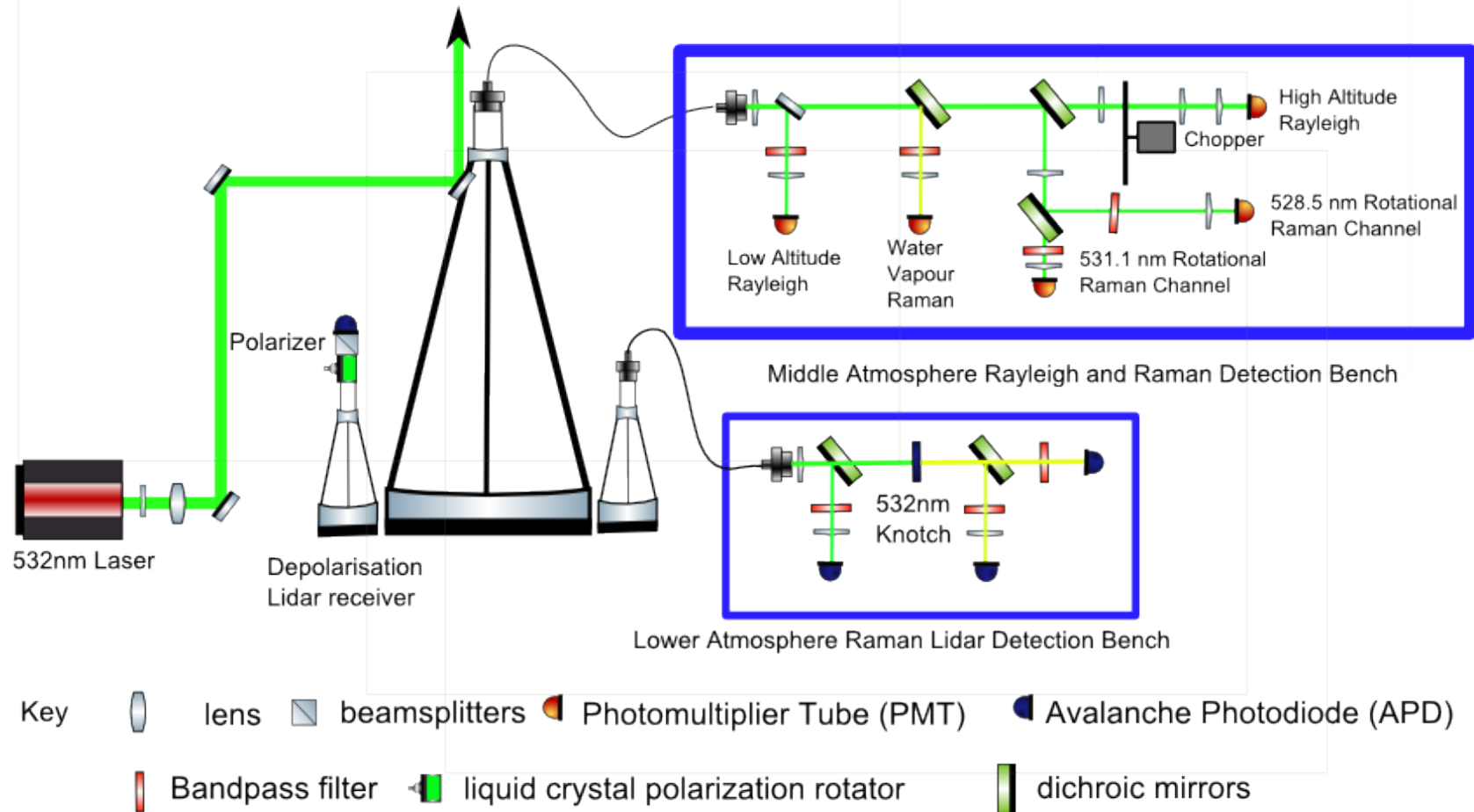
Next?

- Use weaker absorption line
 - 822.922 nm better suited to very dry environments
- Receiver efficiency needs work
- Better control of ASE to improve spectral purity
- Background city light is a major limitation to range
 - reduce receiver FoV?

- And after that
 - DFB diode technology?
 - Engineer for the field?
 - Try operation further inland?
 - Long-range system using higher power lasers?

Rayleigh/Raman Lidar

System schematic



Profiling the Atmosphere

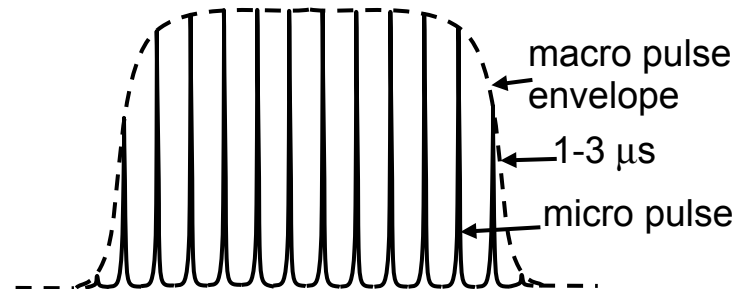
- Rayleigh lidar allows investigation of middle atmosphere (30-80 km)
 - temperature, pressure, density, gravity waves, tidal effects ...
 - with high spatial and temporal resolution
- Raman (+ Rayleigh) lidar used for < 30 km
- Being assembled at Buckland Park Lidar Facility
- Status:
 - laser (Powerlite DS9000: 532nm, 0.5 J, 5 ns, 50 Hz PRF) installed,
 - objective (area = 0.7 m²) in place,
 - receiver electronics currently being developed
- Also, we have started developing an all-solid-state Alexandrite laser for Fe Boltzmann lidar profiling of the MLT (80-100 km)

Na Guide-Star Laser

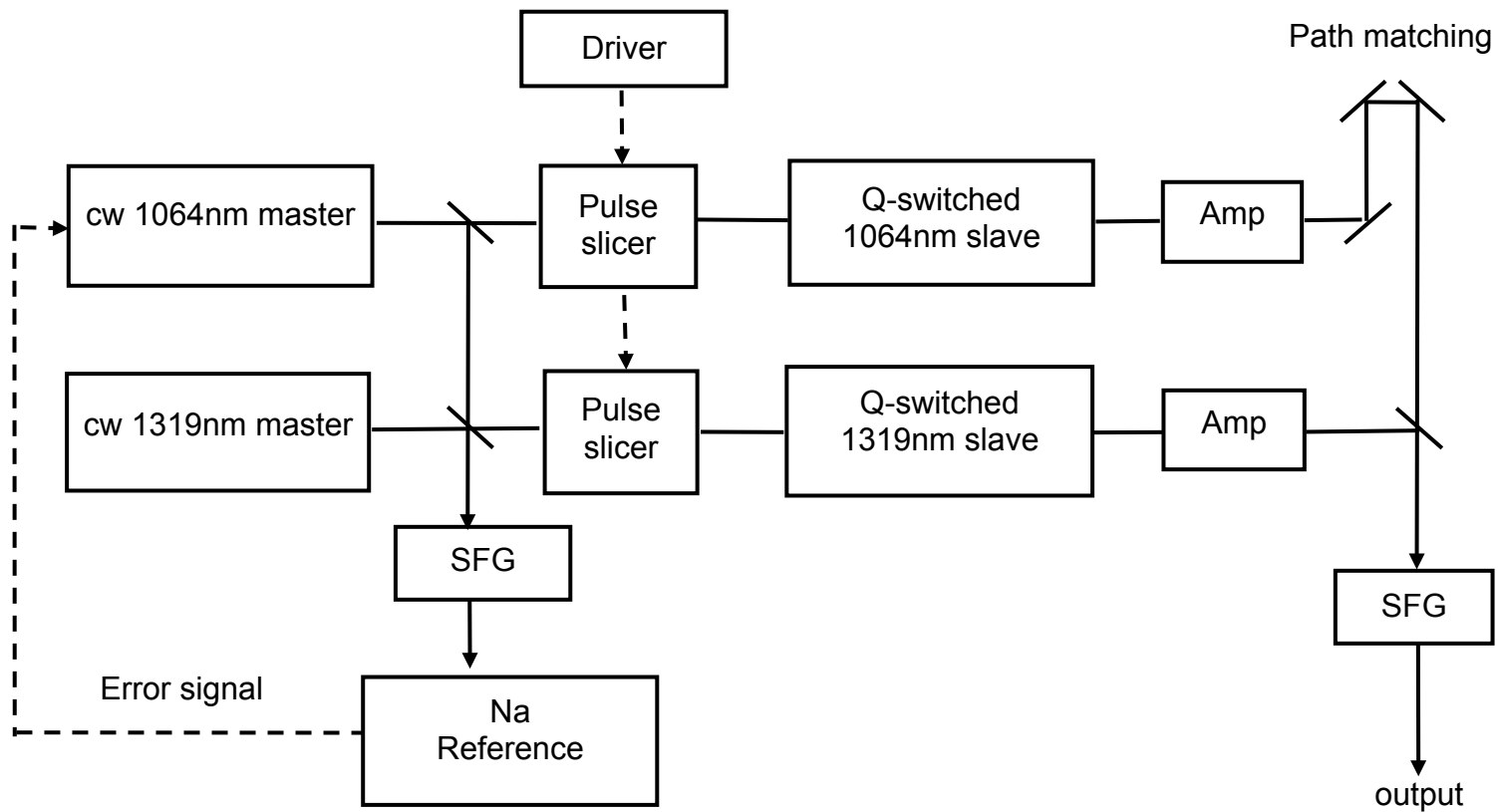
ELT laser guide-star requirements

- Wavelength: 589 nm (sodium D2a resonant)
- Pulse width: 1-3 μs - avoid elongation
- PRF: 800 Hz - range gate
- Bandwidth: 1-3 GHz - excite all Na – but it is easy to saturate!
- Beam quality: <1.2 - small, bright LGS
- Output power: ≥ 50 W
- Robust, all solid state, efficient, reliable

- Potential pulse shape:

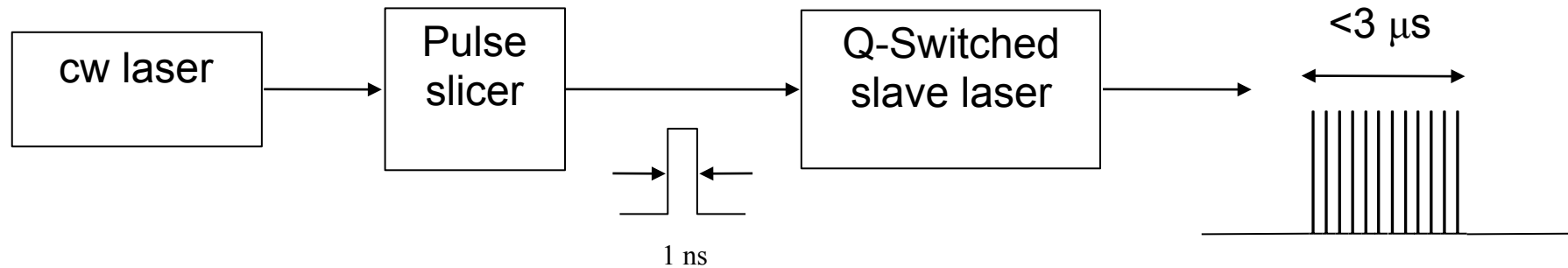


Na-resonant laser approach



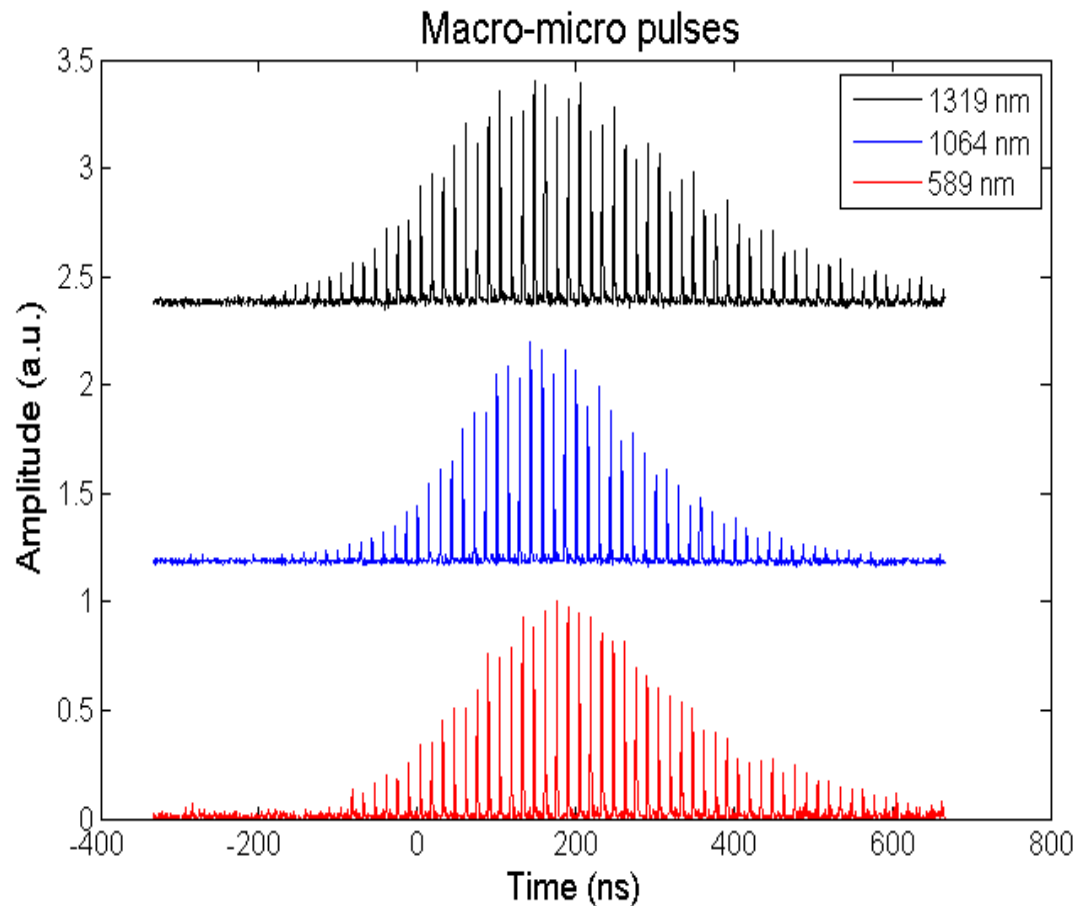
SFG (1064 nm + 1319 nm \rightarrow 589 nm) uses single-pass LBO

Injection mode-locking



- Slice narrow pulse from output of narrow line-width cw master laser
 - Inject pulse into slave laser
 - Pulse seeds multiple longitudinal modes
 - Q-switch laser
 - Output: train of mode-locked pulses under Q-switched envelope
- a “macro-micro” pulse burst

SFG of macro-micro pulse at 589 nm



Input: 11 mJ at 1319 nm
9 mJ at 1064 nm

Output: 6 mJ at 589 nm
(~10 mJ if correct for Fresnel losses)

$M^2 < 1.1$ at 7 W average power

Conversion efficiency ~ 30%

